

**SIEMENS**

# **MAMMOMAT Novation<sup>DR</sup>**

**SP**

## **Wiring Diagrams**

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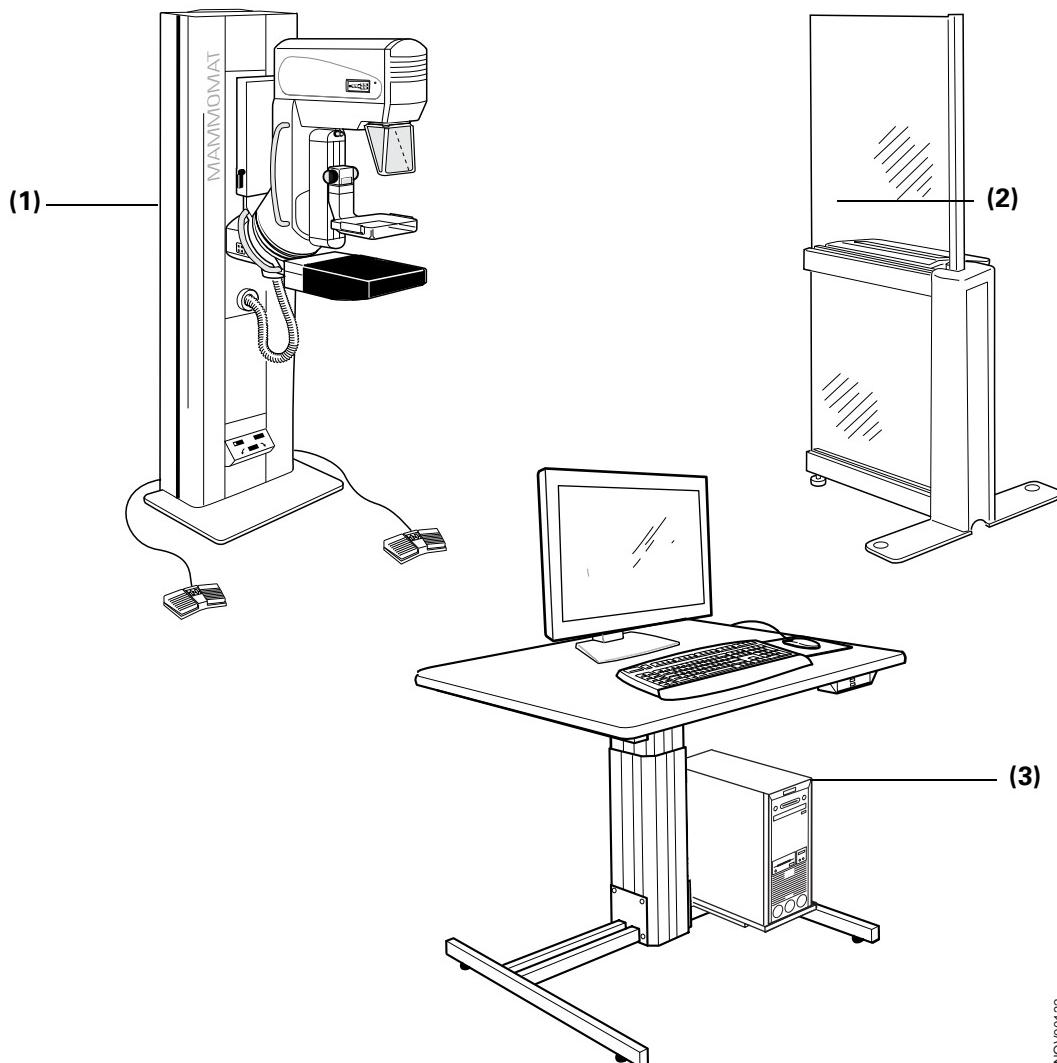
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SYSTEM OVERVIEW

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The Mammomat Novation<sup>DR</sup> system comprises the following:

- X-ray stand and generator with swivel-arm system consisting of X-ray tube assembly and image receptor assemblies (1).
- Radiation shield (option) and control console (2)
- Acquisition workstation with PC, flat screen, keyboard and mouse (3)



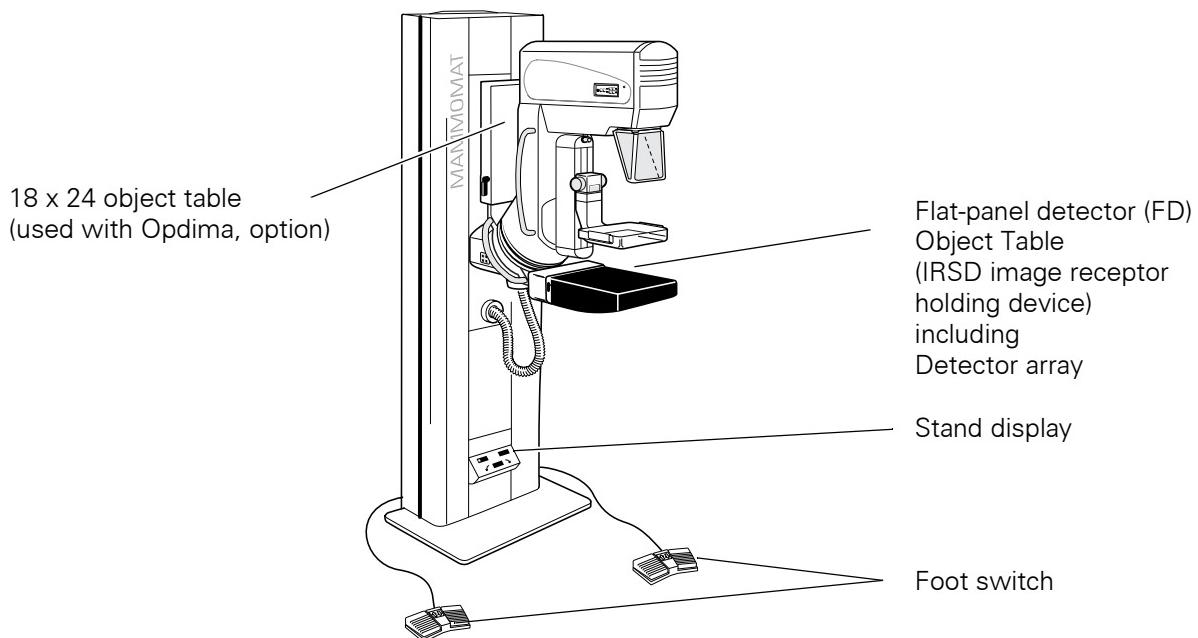
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## SYSTEM OVERVIEW - STAND

Stand with rotating support arm with one FD (Flat Detector) object table and one 18 x 24 object table (used with Opdima, option) and Mo/W X-ray tube.

**⚠ CAUTION**

An 18 x 24 object table shall always be mounted when rotating the Flying-Wing.



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**PLACEMENT OF PC-BOARDS AND COMPONENTS, STAND**


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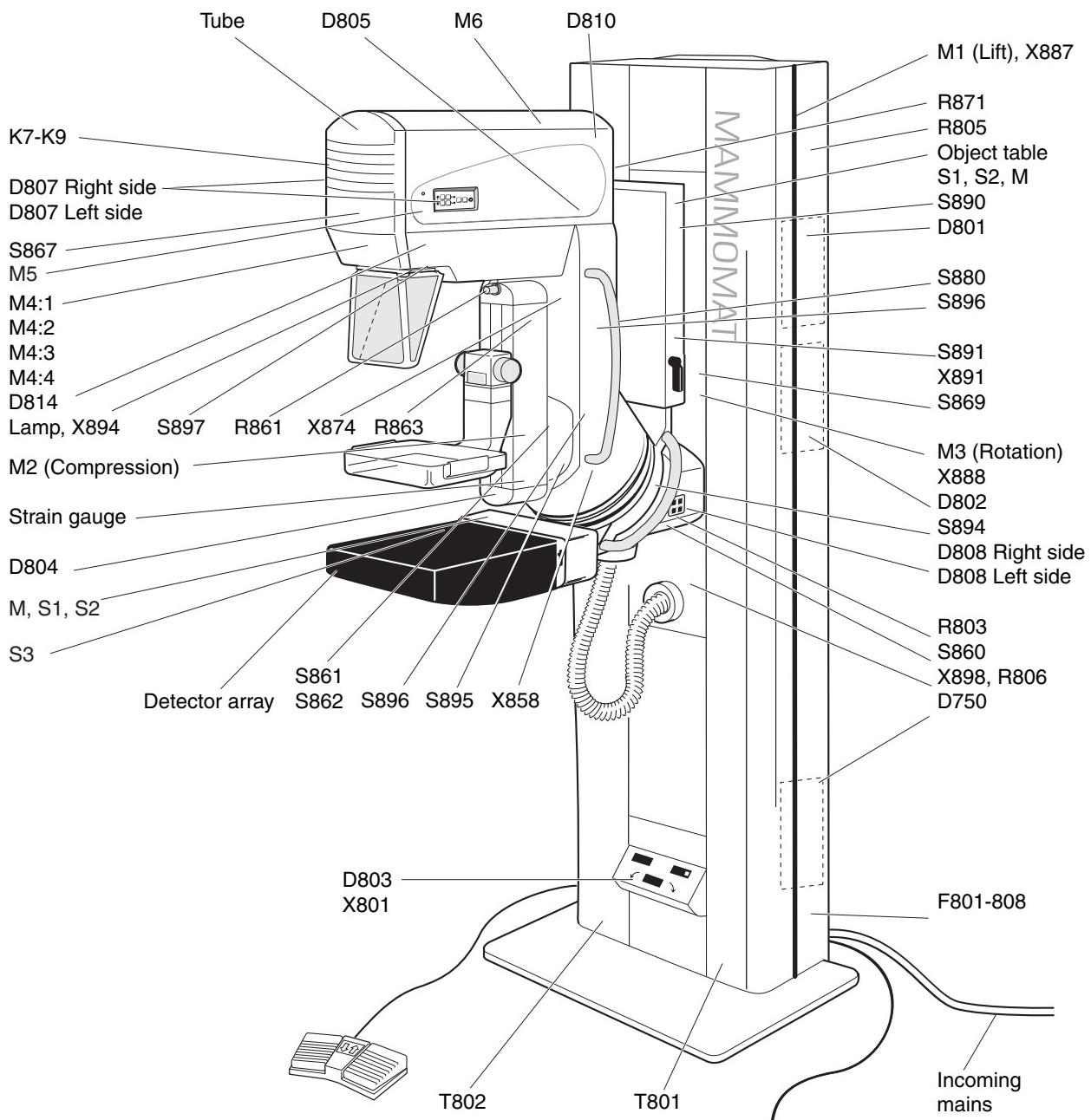
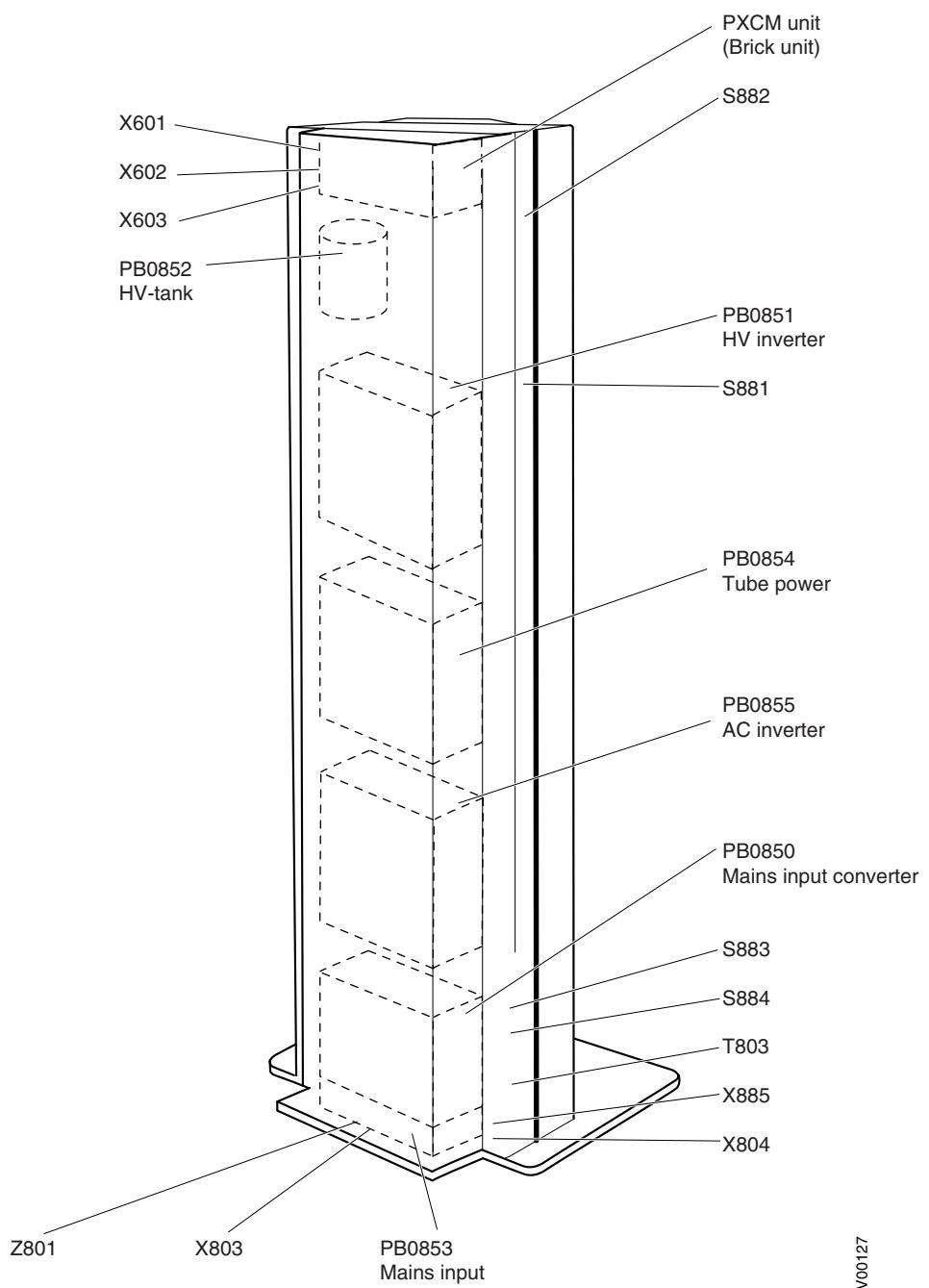
**MAMMOMAT Novation<sup>DR</sup> - Front**


Fig. 1 Front of the stand

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**PLACEMENT OF PC-BOARDS AND COMPONENTS, STAND**


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**MAMMOMAT Novation<sup>DR</sup> - Back (seen from the right side)**


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Fig. 2 Back of the stand (seen from the right)

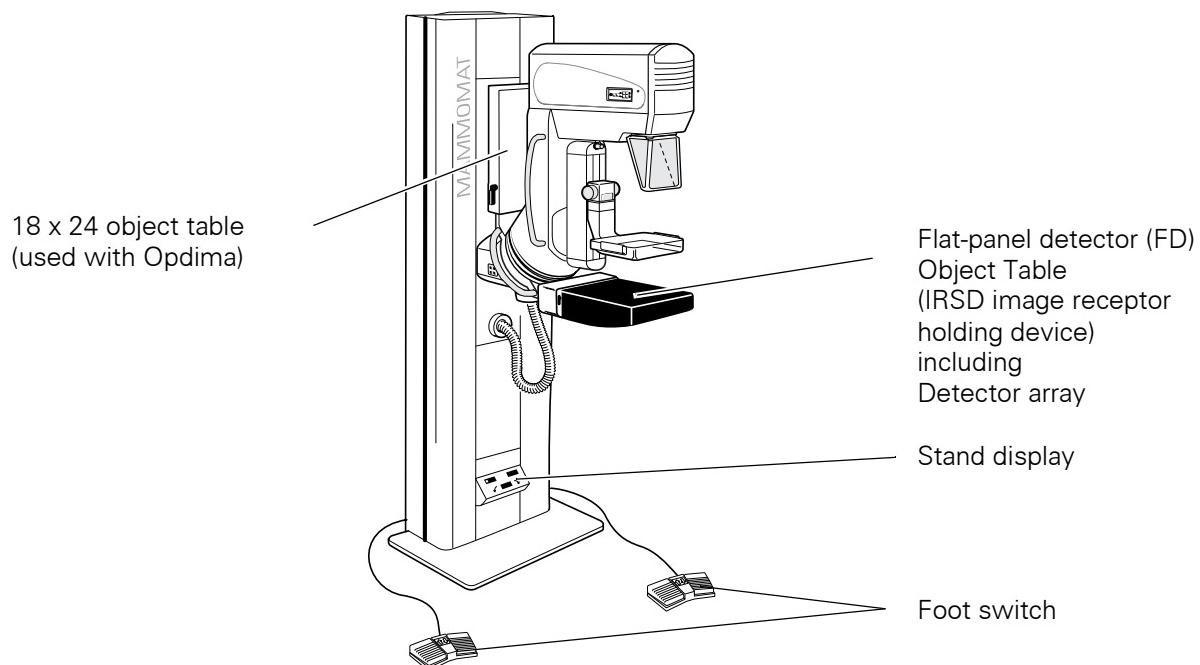
**PLACEMENT OF PC-BOARDS AND COMPONENTS, STAND**

Fig. 3 Stand with rotating support arm

Stand with rotating support arm with one FD (Flat Detector) object table and one 18 x 24 object table (used with Opdima) and Mo/W X-ray tube.

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**LIST OF BOARDS AND FUSES, STAND**


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**PCB Overview**

D750	MASTER BOARD
D801	STAND CPU BOARD
D802	MOTOR CONTROL BOARD
D803	DISPLAY BOARD
D804	FORCE AMPLIFIER BOARD
D805	WING BOARD
D807	BOARD FOR LIFT, ROTATION AND LAMP SWITCHES
D808	BOARD FOR LIFT AND ROTATION SWITCHES
D810	TIlt SWITCH BOARD
D814	COLLIMATOR CONTROL BOARD

**Fuses Overview**

PCB	FUSE	FUSED VOLTAGE
D750	F1 0.5 A	10.5 VAC
D750	F2 0.5 A	10.5 VAC
D801	F1 2 AT	+5V, +5V_REF, +5V_DSP, +7V
D801	F2 1 AT	+5V_MPS
D802	F1 5 AT	+5V, +5V_M, +14V, D805/+5V
D802	F2 3.15 AT	+24VF, +15V
D802	F3 6.3 AT	+24V
D802	F5 5AT	17VAC (LAMP)
D802	F4 1 AT	24VACF (FAN)
<b>Chassis-mounted fuses</b>		
	F801 2 AT	11 VAC
	F802 1 AT	11 V_MPS
	F803 5 AT	14 VAC
	F804 5 AT	17 VAC
	F805 6.3 AT	24 VAC
	F806 1AT	18 VAC
	F807 2AT	400 VAC
	F808 2AT	400 VAC
<b>Brick unit-mounted fuses</b>		
	2 AT	230 VAC
	2 AT	230 VAC

NOTE! See spare parts list for replacement fuses.

**LIST OF SWITCHES AND COMPONENTS, STAND****Switches**

<b>Switch</b>	<b>Page</b>	<b>Description</b>
S1/D801	3-6/1D	Reset switch for stand CPU.
S1/Object table 1	3-17/3A	Grid out switch located in the object table 1.
S1-1-4/D802	3-9/2D	Current limit switches: 1=+3%, 2=+6%, 3=+12%, 4=+24%.
S1-5/D802	3-9/2D	Tacho On/Off switch for rotation motor drive.
S1-S6/D807	3-10/3A	Control switches for lamp, lift- and rotation movement. Left and right side.
S1-S4/D808	3-10/4A	Control switches for lift- and rotation movement. Left and right side.
S2/Object table 1	3-17/2A	Cassette inserted switch.
S860	3-17/3C	Stereo lever switch.
S861	3-13/1G	Compression limit switch, compression unit.
S862	3-13/2G	Decompression limit switch, compression unit.
S867	3-16/3G	Filter / mirror disk micro switch.
S869	3-8/3G	Tacho optoswitch
S880	3-4/2B	Emergency stop, switches off 24VAC and 14VAC, machine blocked.
S881	3-9/1G	Lift up limit switch, rotating unit.
S882	3-4/2A	Limit switch, distance tube head - floor <50 mm, switches off 24VAC, machine blocked.
S883	3-8/4B	Collision protection switch, risk of collision when tubehead is less than 120 mm from the floor.
S884	3-9/2G	Lift down limit switch, rotating unit.
S890	3-17/3C	AEC in position switch (Wing 1) (Not used).
S891	3-17/3C	Object table locked in position (Wing1).
S894	3-17/4C	Select wing 1 switch.
S895	3-17/4C	Select wing 2 switch.
S896	3-14/4A	Tilt opto-switch. 0 or ±10 .
S897	3-16/2G	Diaphragm switch.
S1	3-17/1A	Grid out switch located in object table 2.
S2	3-17/2A	Grid front switch located in object table 2.
S3	3-17/2A	Grid rear switch located in object table 2.

**LIST OF SWITCHES AND COMPONENTS, STAND****Potentiometers**

<b>Potentiometer</b>	<b>Page</b>	<b>Description</b>
R803	3-14/2A	Tube angle, 2k.
R861	3-12/2E	Preset force, 10k.
R863	3-12/2E	Thickness, 2k.
R871	3-14/2A	Preset angle, 10k.

**Motors**

<b>Motor</b>	<b>Page</b>	<b>Description</b>
M	3-17/1A	Grid motor, placed in object table with grid.
M1	3-9/2G	Lift motor.
M2	3-13/2G	Compression motor.
M3	3-9/2G	Rotation motor.
M4 :1, :2, :3, :4	3-16/5E	Collimator stepping motor.
M5	3-16/4G	Filter / mirror disk step motor.
M6	3-7/4G	Fan, tube cooling.
M9	3-9/5G	Rotation brake.
M10	3-9/5G	Rotation brake.

**Miscellaneous**

<b>Misc.</b>	<b>Page</b>	<b>Description</b>
COMP. UNIT	3-12	Compression unit.
GROUND RAIL	3-2/1E	System grounding terminal.
K7	3-7/4E	Fan thermostat.
K8	3-7/4E	Tube overtemperature thermostat.
K9	3-7/4E	Tube housing overpressure switch.
L804 - L805	3-13/2G	VHF choke (EMC)
L806 - L809	3-9/2G	VHF choke (EMC)
LAMP	3-15/5G	Field light lamp.
R805	3-9/5G	Brake resistor, 6.2Ω
R806	3-9/5G	Brake varistor
R807	3-9/1G	Lift motor varistor.
R860	3-12/2A	Strain gauge (R=300-400 Ω)
T801	3-3/2C	Mains transformer.
T802	3-3/3C	Transformer for PXCM unit (Brick unit)
T803	3-3/3C	Transformer for Opdima system
Z801	3-3/4C	Filter for Opdima system
C801 - C803	3-13/4G	EMC capacitors

**LIST OF SIGNALS AND TEST POINTS, STAND**

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## LIST OF SIGNALS AND TEST POINTS, STAND

Page	Signal Name	Origin	Via	Destination	Testpoint	LED
3-9/1C	ACT_SPEED	TACHO		D802	ACT_SPEED	
3-17/3C	AEC_POS	S890	D805	D801		
3-10/1A	ANGLE_MEM	D807	D805	D801		
3-12/3B	BR_OPEN	D804			D804.X843 pin 8	V2
3-12/3B	BR_RET	D804			D804.X843 Pin 7	
3-9/4B	*BRAKE	D801		D802		
3-9/4E	*BRAKE_RET	D802		M9, M10	D802 BRAKE_RET	
3-9/4E	*BRAKE_RELAY	D802		D802		
3-9/4E	C_LIM	D802				V11
3-13/2D	C_PWM	D802		M2	D802 C_PWM	
3-17/3C	CASS_LOADED	OBJ. TABLE 1	D805	D801		
3-16/2F	COLL_MOT_INT	D814	D805	D801		
3-16/2D	COLL_MOT_RX					
3-16/2C	COLL_MOT_TX					
3-13/1E	COMP_LIMIT	D802	D805	COMP. UNIT		
3-13/2B	*COMP_DIR	D801		D802	D802 COMP_D	
3-12/3C	COMP_FORCE	D804		D801	D804.X843 pin 5	
3-13/3E	COMP_OK	D802		D801		D802 V2 COMP_ERR
3-13/1E	COMP_PROT	D802		D801	D802 COMP_PROT	
3-13/2B	*COMP_SPEED	D801		D802	D801, D802 COMP_SP	
3-13/4F	COMPRESS	PEDAL	D805	D801, D802		
3-9/2D	D_PWM	D802			D802 D_PWM	
3-13/1E	DECOMP_LIMIT	D802	D805	COMP. UNIT		
3-13/5F	DECOMPRESSION	PEDAL / **		D801, D805		
3-9/3B	*DIR	D801		D802	D802 DIR	
3-9/3F	DRIVE_OK	D802		D801		D802 V24DRIVE_ERR
3-9/1E	DRIVE_PROT	D802		D801	D802 DRIVE_PROT	
3-16/1G	EXT_COLL	S897	D805	D801		
3-16/2F	FILT_MOT_INT	D814	D805	D801		
3-16/2D	FILT_MOT_RX					
3-16/2C	FILT_MOT_TX					
3-16/4G	FM OUT 1A	D814		M5		
3-16/4G	FM OUT 1B	D814		M5		
3-16/4G	FM OUT 2A	D814		M5		
3-16/4G	FM OUT 2B	D814		M5		

“\*SIGNAL” = “SIGNAL” active low

\*\*plus decompression button on control console S3.

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**LIST OF SIGNALS AND TEST POINTS, STAND**


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<b>Signal Name</b>	<b>Description</b>
ACT_SPEED	Test point for frequency to voltage converted tacho signal.
AEC_POS	AEC-detector in position near breast (not used).
ANGLE_MEM	Operator control signal for preset stop angle.
BR_OPEN	Bridge open, compression force strain gauge not working correctly.
BR_RET	Compression force strain guage return line (appr. 0V).
*BRAKE	Control signal to brake reversing relay.
*BRAKE_RET	Output to the brakes for max or min braking when active.
*BRAKE RELAY	Output to brake reversing relay, max brake if *BRAKE_RET active.
C_LIM	Rotation and fast-acting current limit.
C_PWM	Pulse Width Modulated power output to compression motor.
CASS_LOADED	Cassette inserted in object table 1 (not used).
COLL_MOT_INT	Collimator motor interrupt signal.
COLL_MOT_RX	Collimator motor receive signal.
COLL_MOT_TX	Collimator motor transmit signal.
COMP_LIMIT	Power output via compression limit switch to compression motor.
*COMP_DIR	Controls compression motor to compress (moving down).
COMP_FORCE	Analog signal indicating compression force.
COMP_OK	Compression motor working correctly, no over current.
COMP_PROT	Compression relay K4 is working correctly, checked 1s after pedal release.
*COMP_SPEED	Pulse Width Modulated signal to control speed of compression motor (20kHz).
COMPRESS	Operator control signal to move compression plate down.
D_PWM	Pulse Width Modulated power output to rotation or lift motor.
DECOMP_LIMIT	Power output via decompression limit switch to compression motor.
DECOMPRESS	Operator control signal to move compression plate up.
*DIR	Selecting direction of rotation or lift motor.
DRIVE_OK	Rotation and lift motor are working correctly, no over current, approx. 1.5 s delay.
DRIVE_PROT	DMG relay K6 is working correctly, checked 3s after rot/lift button is released.
EXT_COLL	External diaphragm switch, diaphragm in place.
FILT_MOT_INT	Filter motor interrupt signal.
FILT_MOT_RX	Filter motor receive signal.
FILT_MOT_TX	Filter motor transmitt signal.
FM OUT 1A	Filter / Mirror disk step motor M5.
FM OUT 1B	Filter / Mirror disk step motor M5.
FM OUT 2A	Filter / Mirror disk step motor M5.
FM OUT 2B	Filter / Mirror disk step motor M5.

**LIST OF SIGNALS AND TEST POINTS, STAND**

<b>Page</b>	<b>Signal Name</b>	<b>Origin</b>	<b>Via</b>	<b>Destination</b>	<b>Testpoint</b>
3-6/3B	GEN_PREP_RDY (VH)	D750		D801	
3-17/2A	GRID_FRONT	OBJ.TABLE 2	D805	D801	
3-17/4D	GRID_MOTOR_N	D802	D805	OBJ. TABLE	D802 GRID_M
3-17/2E	GRID_OUT	OBJ. TABLE	D805	D801	D801 GRID_O
3-6/2B	GRID_RUNNING (AR)	D801		D750	D801 AR
3-17/2A	GRID_REAR	OBJ.TABLE 2			
3-17/3G	*GRID_SPEED	D801		D802	D801 GRID_SP
3-12/3D	I1_OUT	D804			D804.X843 pin 6
3-7/4D	K8_TEMP	TUBE/K8		D750	
3-7/4D	K9_PRESS	TUBE/K9		D750	
3-15/2A	LAMP	D807	D805	D801	
3-15/4C	*LAMP_CTRL	D801		D802	
3-15/5F	LAMP_V	D802		LAMP	D802 LAMP
3-8/3D	LED	D802		TACHO switch	
3-10/3E	LIFT_DOWN	D807, D808	D805	D801, D802	
3-10/3E	LIFT_UP	D807, D808	D805	D801, D802	
3-15/4F	*MIRROR_MAGNET	D802			D802 MIRROR
3-6/3B	MPS	D801		D750	D801 MPS
3-16/5C	OUT 1A	D814		M4:1, :2, :3, :4	
3-16/5C	OUT 1B	D814		M4:1, :2, :3, :4	
3-16/5C	OUT 2A	D814		M4:1, :2, :3, :4	
3-16/5C	OUT 2B	D814		M4:1, :2, :3, :4	
3-9/2C	PGM_SPEED	D802			D802 PGM_SPEED
3-14/2D	POT_RETURN	POT	D805	D801	
3-12/2E	PRES_FORCE	R861		D801	
3-14/1A	PRESET_ANGLE	R871	D805	D801	

"\*SIGNAL" = "SIGNAL" active low

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**LIST OF SIGNALS AND TEST POINTS, STAND**


---

<b>Signal Name</b>	<b>Description</b>
GEN_PREP_RDY (VH)	The stand is informed that the generator has completed its preparation.
GRID_FRONT	Active when the grid is in front position.
GRID_MOTOR_N	Grid motor return line.
GRID_OUT	Active when the grid is not in end position.
GRID_RUNNING (AR)	Signal given to Master Board D750 as exposure request. If grid used, grid has started.
GRID_REAR	Active when the grid is in rear position.
*GRID_SPEED	Pulse Width Modulated signal control speed of grid motor.
I1_OUT	Output signal from compression force preamplifier.
K8_TEMP	Signal from temperature switch K8 on the tube.
K9_PRESS	Signal from the over pressure switch K9 on the tube.
LAMP	Operator control signal for the field light lamp.
*LAMP_CTRL	Signal to switch on the field light lamp.
LAMP_V	Output to the field light lamp.
LED	Output to the LED in the tacho opto switch in the rotation motor.
LIFT_DOWN	Operator control signal to move compression plate down.
LIFT_UP	Operator control signal to move compression plate up.
*MIRROR_MAGNET	Output to mirror magnet. Enabled via *LAMP_CTRL. (not used)
MPS	Multi processor serial communication for information exchange Master - Slaves.
OUT 1A	Collimator stepping motor M4:1, M4:2, M4:3, M4:4.
OUT 1B	Collimator stepping motor M4:1, M4:2, M4:3, M4:4.
OUT 2A	Collimator stepping motor M4:1, M4:2, M4:3, M4:4.
OUT 2B	Collimator stepping motor M4:1, M4:2, M4:3, M4:4.
PGM_SPEED	Test point for duty cycle to voltage converted programmed speed signal.
POT_RETURN	Return line for potentiometers connected to 0VA via a 20Ω resistor.
PRES_FORCE	Analog signal as preset value for maximum compression force.
PRESET_ANGLE	Analog signal as preset value for requested rotation angle.

## LIST OF VOLTAGES AND TEST POINTS, STAND

Page	Signal Name	Origin	Via	Destination	Testpoint	LED
3-13/2D	PU	D802			D802 PU	
3-16/5C	QUAD A	D814		M4:1, :2, :3, :4		
3-16/5C	QUAD B	D814		M4:1, :2, :3, :4		
3-9/4B	*RELEASE	D801		D802	D802 RELEASE	
3-6/1E	*RESET	D801				
3-16/2C	RESET	D801		D805		
3-6/1E	*RESET_HW	D801				
3-6/1E	RESET_SW	D801				
3-10/3A	ROT_CW	D807, D808	D805	D801, D802		
3-10/3A	ROT_CCW	D807, D808,	D805	D801, D802		
3-6/3D	RXD	D801			D801 RXD	
3-9/3B	*SEL_ROT	D801		D802	D802 SEL_ROT	
3-17/4C	SELECT_WING1**	S891, S894	D805	D801		
3-17/4C	SELECT_WING2	S895	D805	Object table 1		
3-16/1D	SMART_RX				D805 SMART_RX	
3-16/2B	SMART_RX_				D801 SMART_RX_	
3-16/1F	SMART_TX				D805 SMART_TX	
3-9/2B	*SPEED	D801		D802	D801, D802 SPEED	
3-6/2B	STAND_REQ_HV_OFF (*KVA)	D801		D750	D801 *KVA	
3-17/4C	STEREO_LEVER	S860	D805	D801		
3-17/1B	TABLE_CONFIG_0...3	OBJ.TABLE	D805	D801		
3-8/3D	TACHO	Tacho switch		D802	D802 TACHO	
3-12/2E	THICKNESS	R863		D801		
3-12/3F	THICKNESS_B	THICKNESS		D801		
3-12/3E	THICKNESS_STE-REO	D801		X885		
3-14/4C	TILT	S896/D810	D805	D801		D810 V8
3-14/2A	TUBE_ANGLE	R803	D805	D801		
3-6/4D	TXD	D801		D750	D801 TXD	
3-12/3C	ZERO	D804			D804.X843 pin 4	

\*\*SIGNAL" = "SIGNAL" active low.

\*\* = Not used

**LIST OF VOLTAGES AND TEST POINTS, STAND**

<b>Signal Name</b>	<b>Description</b>
PU	Pull up signal for error comparators = +15V, +5V, +24V voltages OK.
QUAD A	Collimator stepping motor M4:1, M4:2, M4:3, M4:4.
QUAD B	Collimator stepping motor M4:1, M4:2, M4:3, M4:4.
*RELEASE	Control signal to release the brakes from min or max to permanent magnet braking.
*RESET	Reset signal to the CPU.
RESET	Reset signal to the smart point interface.
*RESET_HW	Reset signal from the CPU to the reset circuit, caused by slave restart and CPU watchdog reset.
RESET_SW	Signal from the reset switch to the CPU via the reset circuit.
ROT_CW	Operator control signal to rotate the x-ray system clockwise.
ROT_CCW	Operator control signal to rotate the x-ray system counter clockwise.
RXD	Input for receiving data via MPS.
*SEL_ROT	Low level signal selects the rotation drive to be controlled.
SELECT_WING1	Signal from select wing 1 switch. Wing 1 selected (not used).
SELECT_WING2	Signal from select wing 2 switch. Wing 2 selected.
SMART_RX	Smart point transmit signal.
SMART_RX_	Smart point receive signal.
SMART_TX	Smart point receive signal.
*SPEED	Pulse Width Modulated signal to control speed of rotation or lift motor (20 kHz).
STAND_REQ_HV_OFF (*KVA)	Signal to terminate exposure. WIRED-OR line, see Master board D750.
STEREO_LEVER	Signal from stereo lever switch, indicating lever not in stereo position.
TABLE_CONFIG	4 inputs from object table, see table configuration .
TACHO	Signal from rotation motor tachometer.
THICKNESS	Analog signal indicating the compression thickness.
THICKNESS_B	Buffered output to the thickness adapter. (used with Opdima)
THICKNESS_STEREO	Isolated analog signal indicating compression thickness for stereo evaluation unit.
TILT	Indicates that the stereo angle is 0° or ±10°. Visible through vent opening behind tube.
TUBE ANGLE	Analog signal indicating the rotation angle.
TXD	Output for sending data via MPS.
ZERO	Used for adjusting offset of the compression force amplifiers.

## LIST OF VOLTAGES AND TEST POINTS, STAND

Page	Voltage	Origin	Supplied from	Supply for	Test	LED	Fuse
3-3/4E	+5V	D801	11V	Digital IC, +5V_REF	5V	V7	D801/F1 F801
3-3/4F 3-12/3C	+5V_REF	D801	+5V	Pots. D804	5V_REF X843 pin 2		D801/F1 F801
3-3/3E	+5V_DSP	D801	11V	D803, Display	5V_DSP	V6	D801/F1 F801
3-3/2E 3-12/3B	+7V	D801	11V	Analog IC, D804	7V X843 pin1	V5	D801/F1 F801
3-6/4D	+5V_MPS	D801	11V_MPS	Generator interface	5V_MPS	V26	D801/F2 F802
3-3/3D	0VD	GND	D801/X811	Digital IC	0VD1,OVD2		
3-3/3D 3-12/3B	0VA	0VD	D801	Analog IC D804	0VA1 X843 pin 3		
3-6/5D	0V_MPS	D750/GND		Generator inter- face ground	D801 MPS		
3-3/2C	11V	T801	230VAC	+5V, +5V_DSP, +7V			D801/F1 F801
3-6/5B	11V_MPS	T801	230VAC	+5V_MPS			D801/F2 F802
3-4/4D	+5V	D802	14VAC	Digital IC	5V	V57	D802/F1 F803
3-4/4E	+5V_M	D802	+5V	D801-D802 opto interface		V57	D802/F1 F803
3-2/5C	0V_W	D801	D805/X856	Optointerface			
3-2/4C	0V_M	D801	D802/X822	Optointerface			
3-4/3D	+14V	D802	14VAC	+5V, D805	14V		D802/F1 F803
3-4/2D	+15V	D802	+24VF	Transistor drivers M1,M3	15V	V16	D802/F2
3-4/2C	+24V	D802	24VAC	+15V			D802/F3 F805
3-4/2D	+24VF	D802	+24V	Switches, relays, etc	24VF		D802/F2
3-4/3A	14VAC	T801	230VAC	+14V			D802/F1 F803
3-15/5B	17VAC	T801	230VAC	LAMP	17VACF		D802/F5 F804
3-15/4E	17VACF	D802	17VAC	LAMP	17VAC_RET		D802/F5 F804
3-15/4D	0V_L	D802	D802	Lamp control			
3-15/5D	-V_L	D802	17VACF	Lamp control			
3-4/2A	24VAC	T801	230VAC				D802/F3 F805
3-4/2E	24VACF	D802	24VAC	Fan			D802/F4
3-4/3D	0V	GND	D802/X821	Ground	0V, 0V1		
3-4/G2	+5V	D805	D802/+14V	Digital IC	5V	V17	D802/F1 F803
3-4/2G	+12V	D805	+14V	V_MOT D814	12V		D802/F1 F803
3-4/2G	+5V_SP	D805	D802/+14V	Digital IC	5V_SP		D802/F1 F803
3-4/2G	8,2V_SP	D805	D802/+14V	Digital IC	8,2V_SP		D802/F1 F803

**LIST OF VOLTAGES AND TEST POINTS, STAND**

<b>Voltage</b>	<b>Description ( typical value)</b>
+5V	Regulated DC voltage, 4.75V < +5V < 5.25V
+5V_REF	DC voltage, +5V -5% < +5V_REF < +5V
+5V_DSP	Regulated DC voltage, 4.75V < +5V_DSP < 5.25V
+7V	Regulated DC voltage, 6.60V < +7V < 7.25V
+5V_MPS	Regulated DC voltage, 4.75V < +5V_MPS < 5.25V
0VD	Digital ground
0VA	Analog ground
0V_MPS	Generator interface ground.
11V	AC supply voltage, 11VAC <sup>1) 2)</sup>
11V_MPS	AC supply voltage, 11VAC <sup>1) 2)</sup>
+5V	Regulated DC voltage, 4.75V < +5V < 5.25V
+5V_M	Regulated DC voltage, 4.75V < +5V_M < 5.25V
0V_W	Digital ground optointerface D801 - D805
0V_M	Digital ground optointerface D801 - D802
+14V	Unregulated DC voltage, 18V <sup>1)</sup>
+15V	Regulated DC voltage, 14.25V < +15V < 15.75V
+24V	Unregulated DC voltage, 32V <sup>1)</sup>
+24VF	Unregulated DC voltage, 32V <sup>1)</sup>
14VAC	AC supply voltage, 14 VAC <sup>1) 2)</sup>
17VAC	AC supply voltage, 17 VAC <sup>1) 2)</sup>
17VACF	AC supply for lamp <sup>1)2)</sup>
0V_L	Floating ground for LAMP voltage regulation <sup>1)2)</sup>
-V_L	Unregulated supply voltage for lamp control circuit <sup>1)2)</sup>
24VAC	AC supply voltage, 24VAC <sup>1) 2)</sup>
24VACF	AC supply voltage for the fan <sup>1) 2)</sup>
0V	Circuit ground
+5V	Regulated DC voltage, 4.75V < +5V < 5.25V
+5V_R	Regulated DC voltage, 4.40V < +5V_R < 5.25V
+5V_SP	Regulated DC voltage, 4.85V < +5V < 5.15V
8.2V_SP	Regulated DC voltage, 7.8V < +8.2V < 8.6V

<sup>1)</sup> Standby typical value

<sup>2)</sup> Floating voltage. Measure differentially.

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**LIST OF VOLTAGES AND TEST POINTS, STAND**

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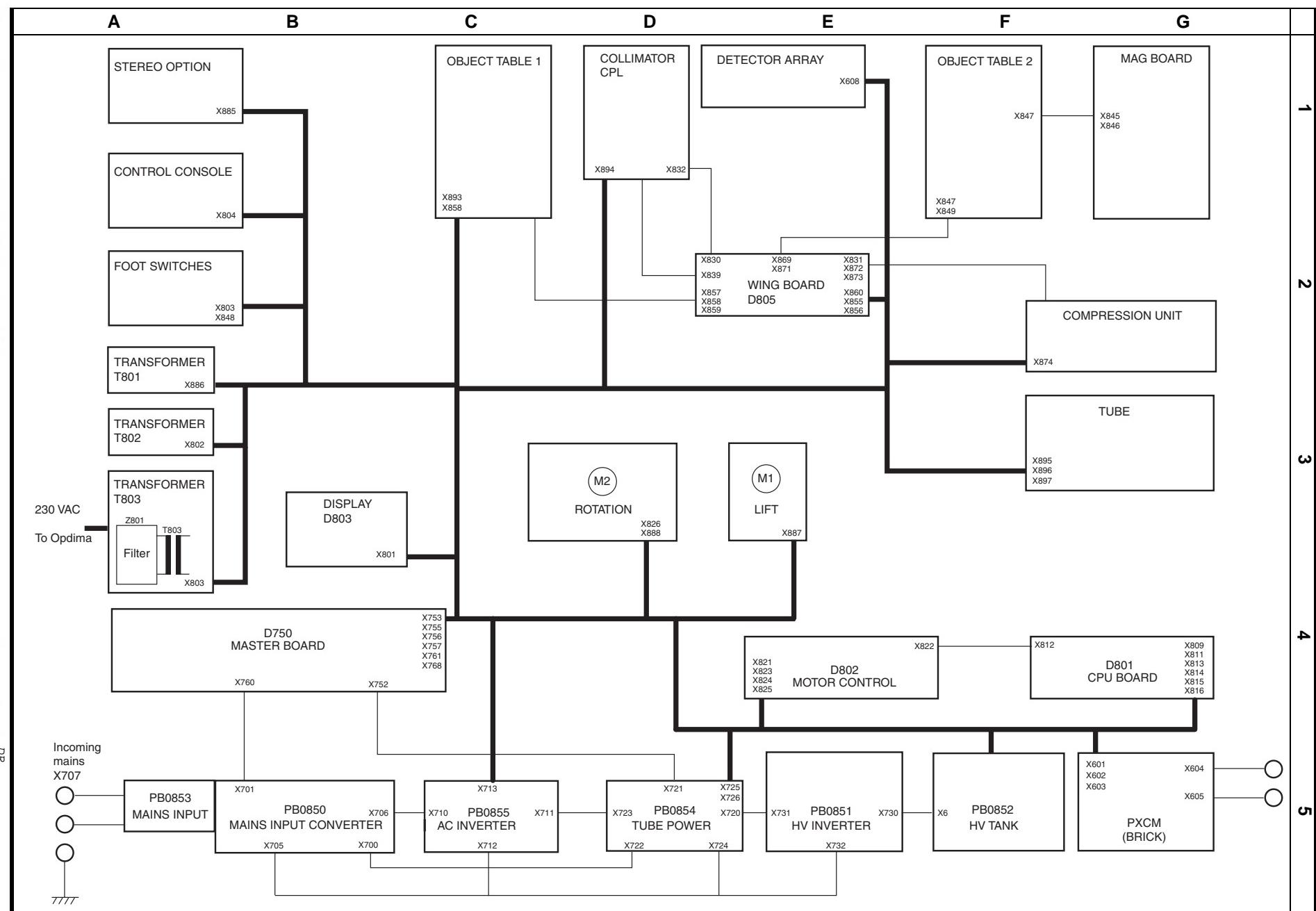
**NOTE**

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For incoming mains voltage, see page 4-1.

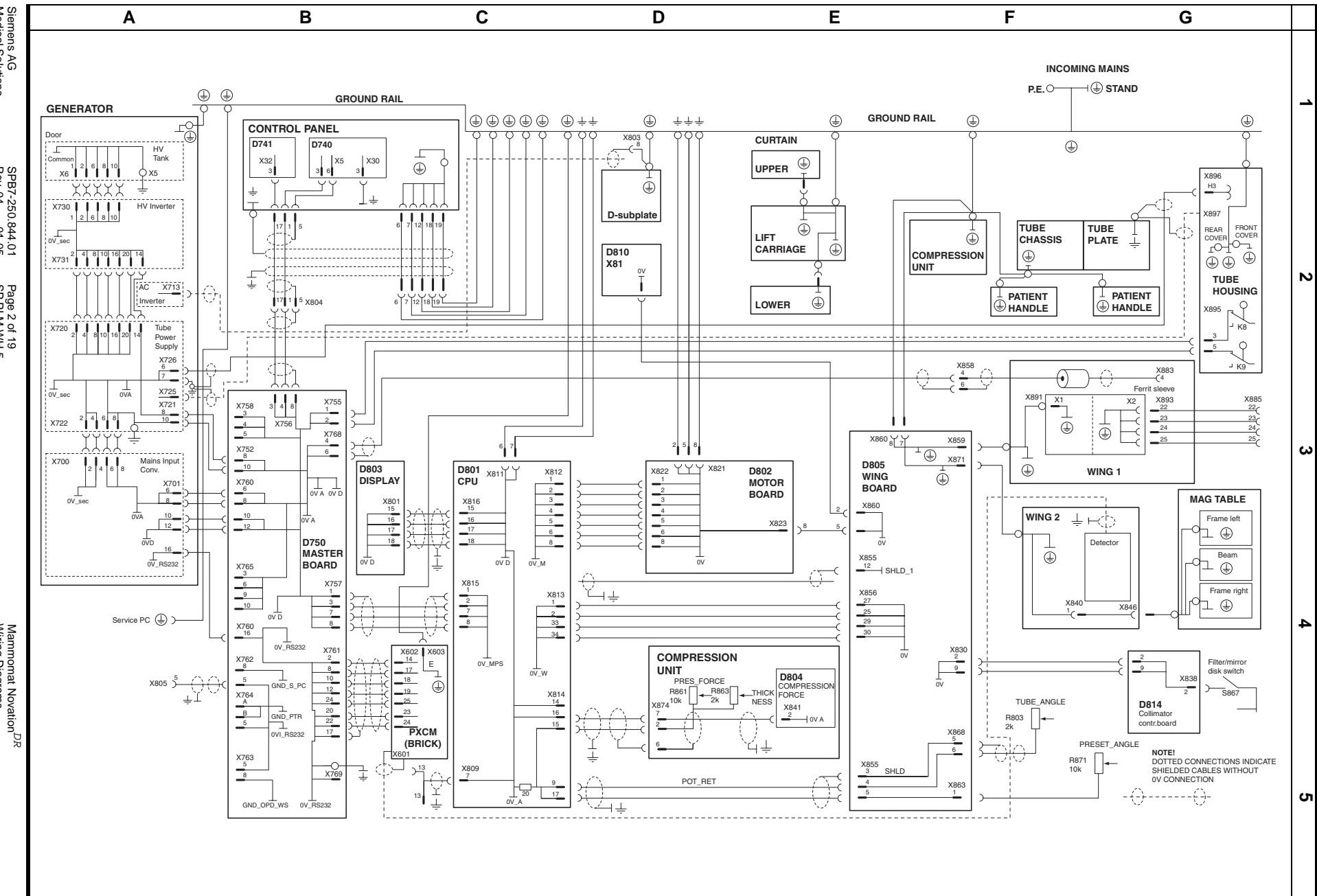
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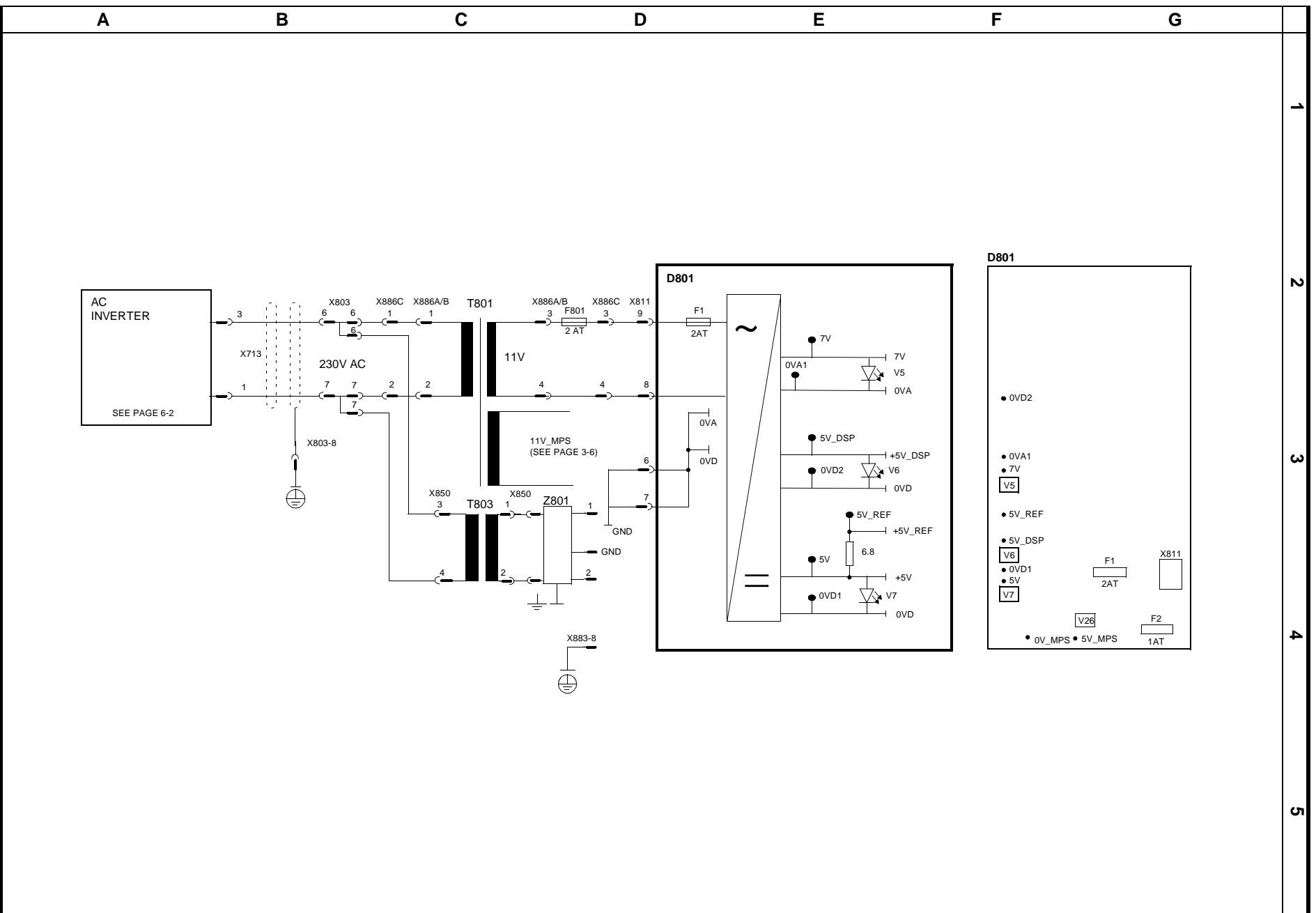
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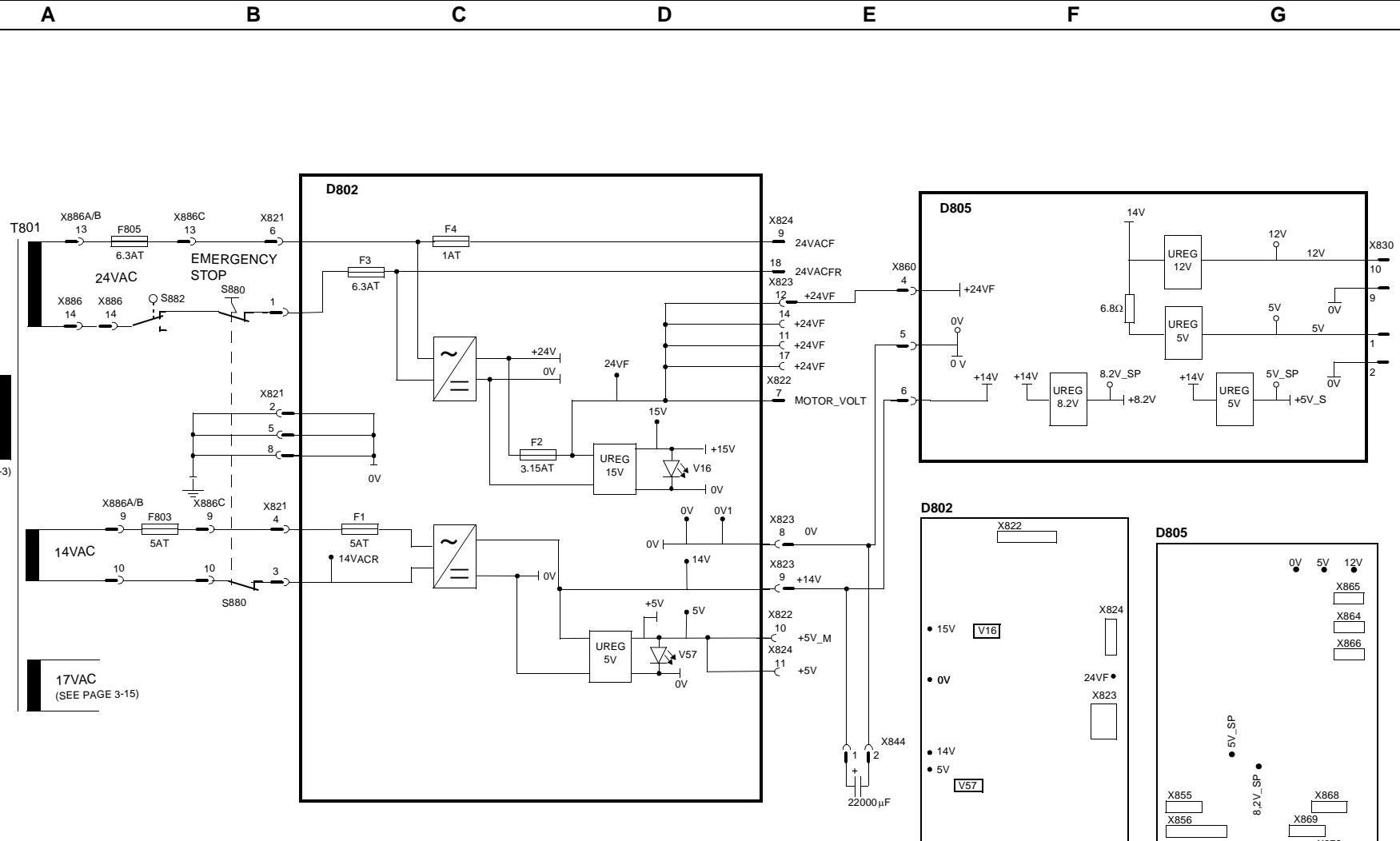


## GROUNDING CONNECTIONS

X041E







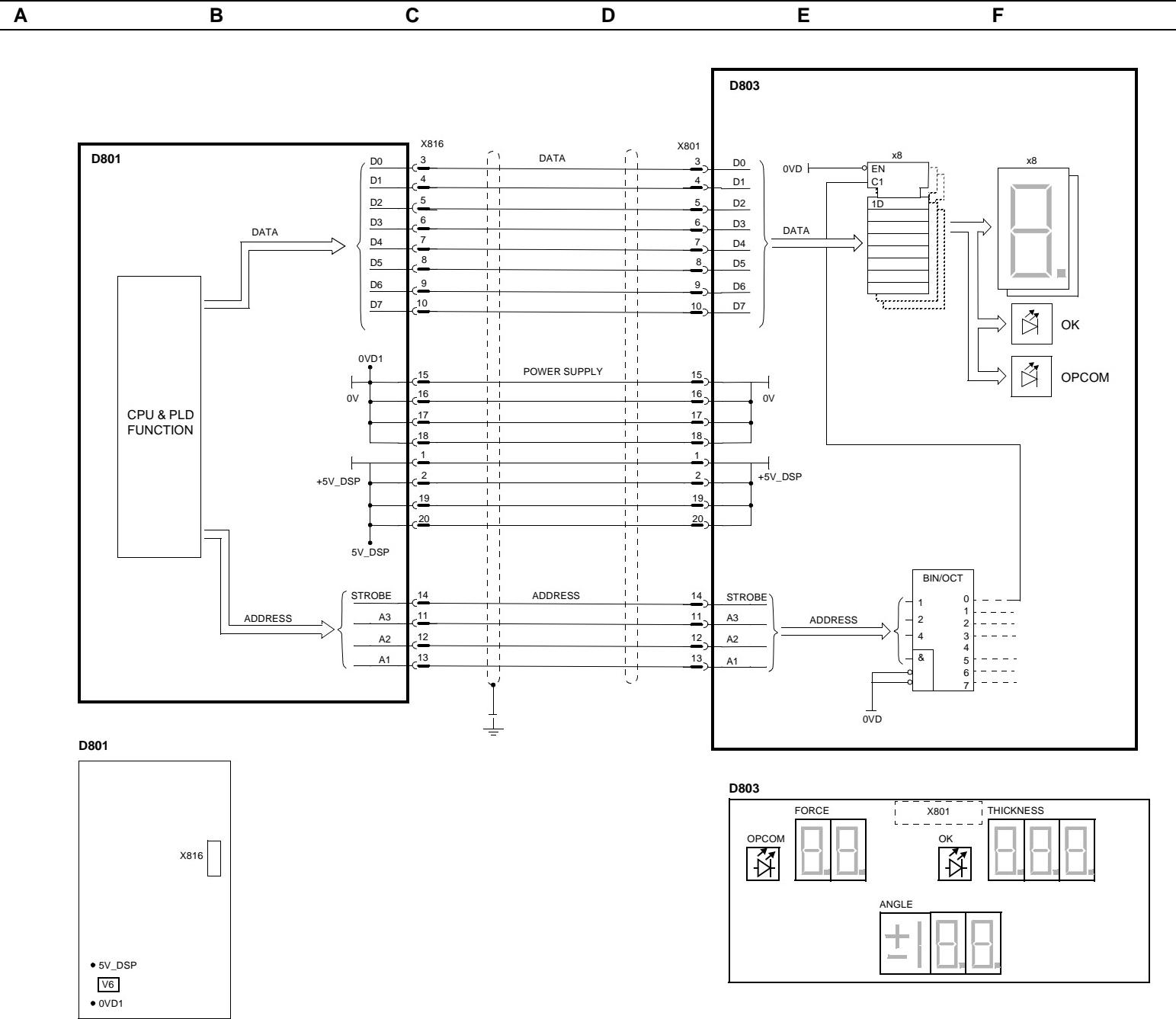
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Wiring Diagrams

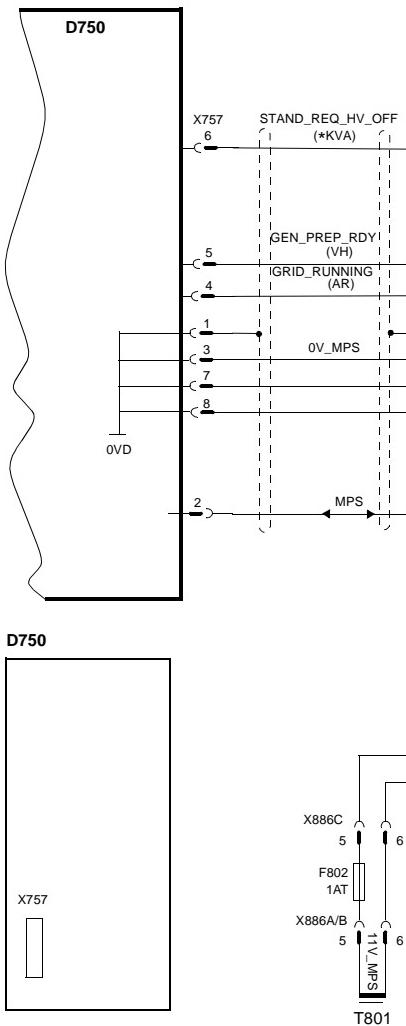
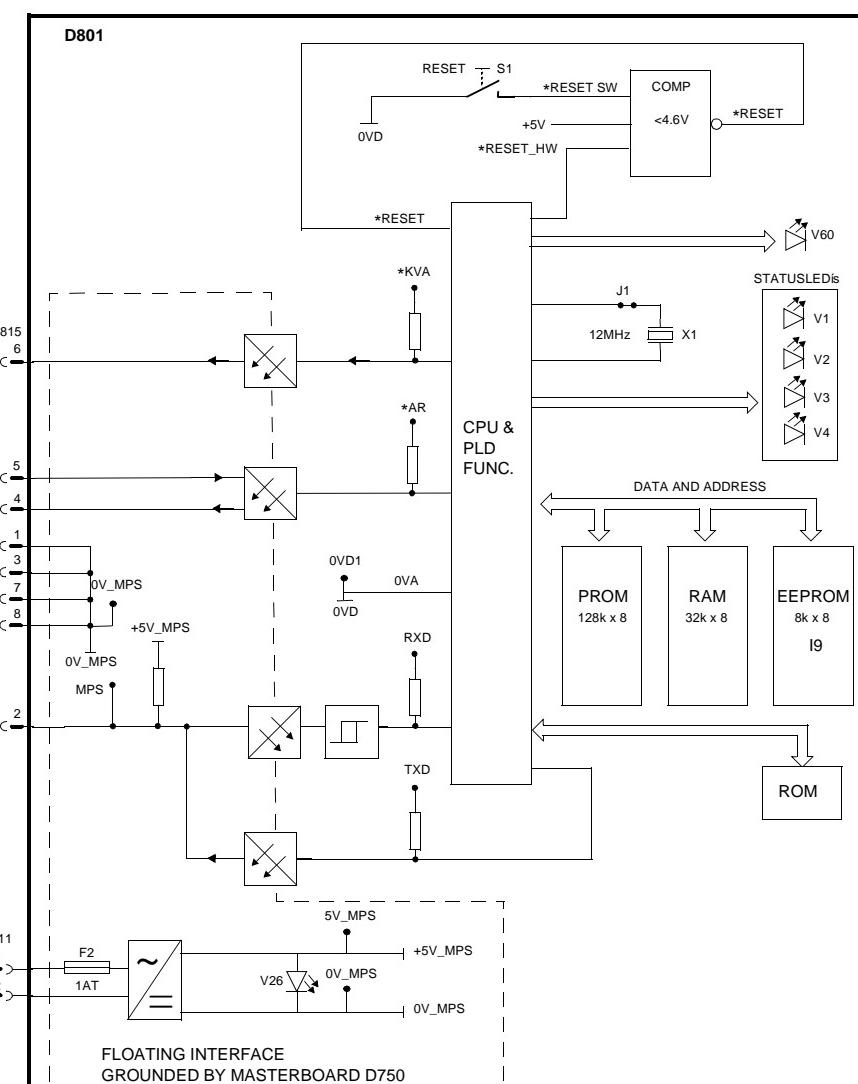
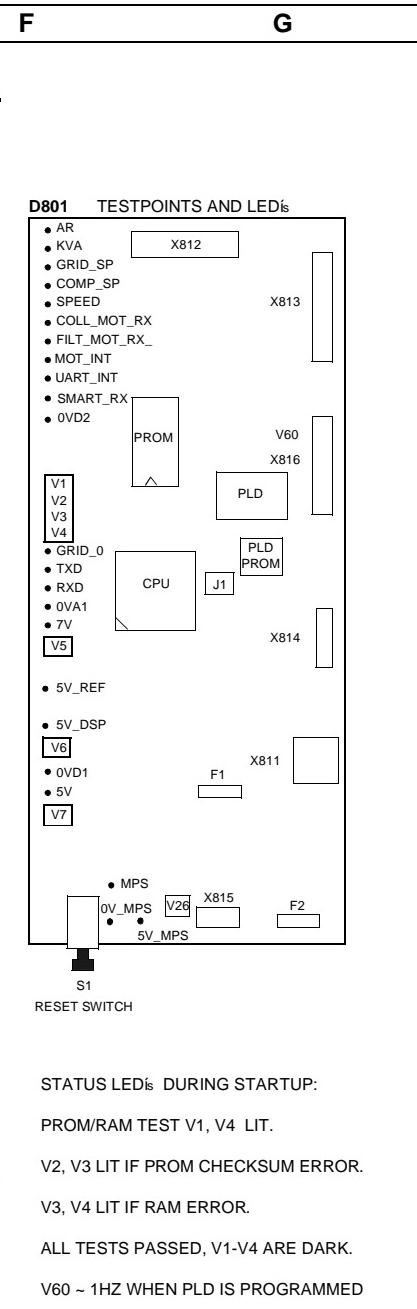
# X041E DISPLAY

3-5



## CPU BOARD INTERNAL, MASTERBOARD INTERFACE

1  
2  
3  
4  
5  
6



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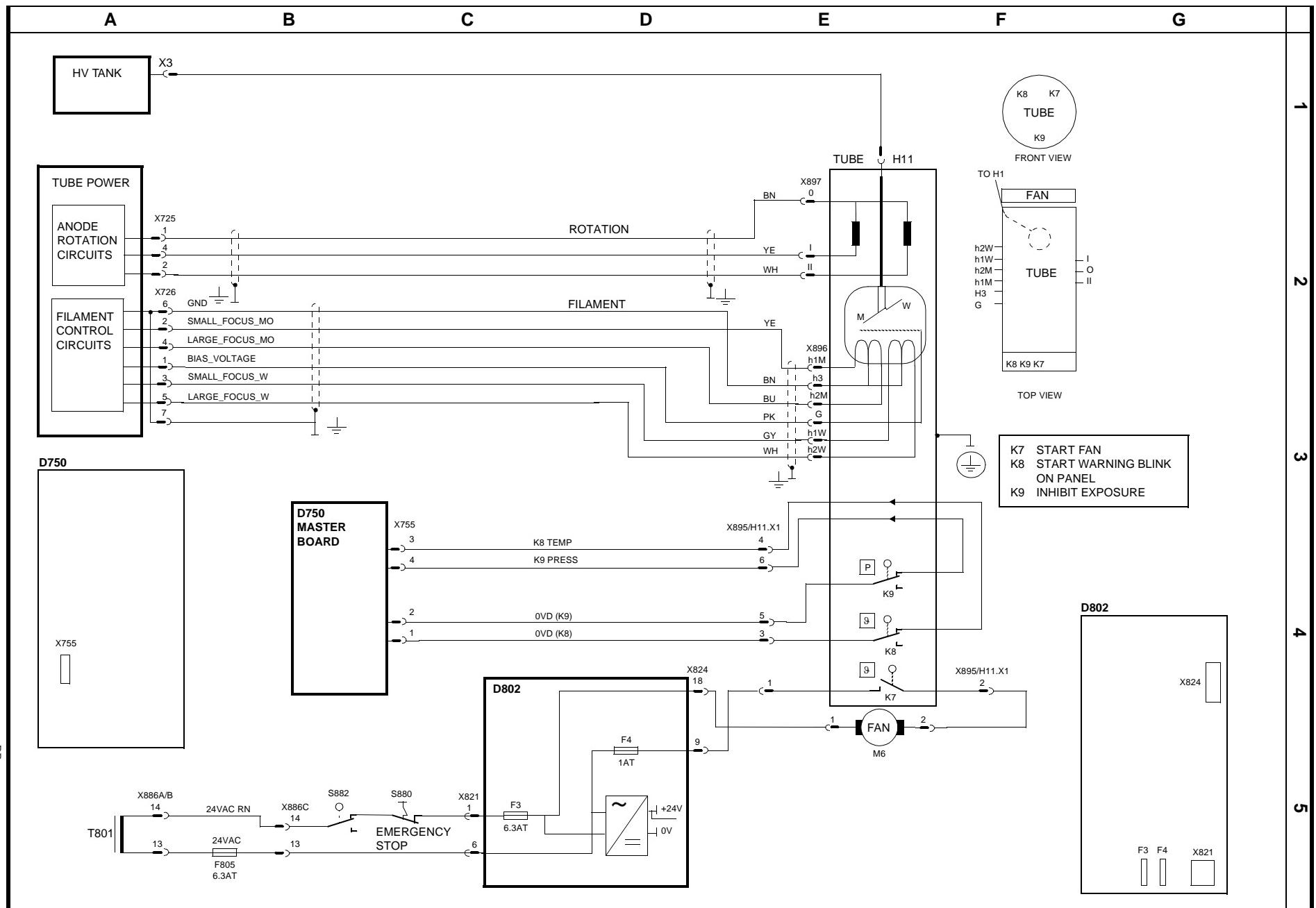
Rev. 04 01.05

SPPM WH 5

Wiring Diagrams

# X041E TUBE, TEMPERATURE MONITORING

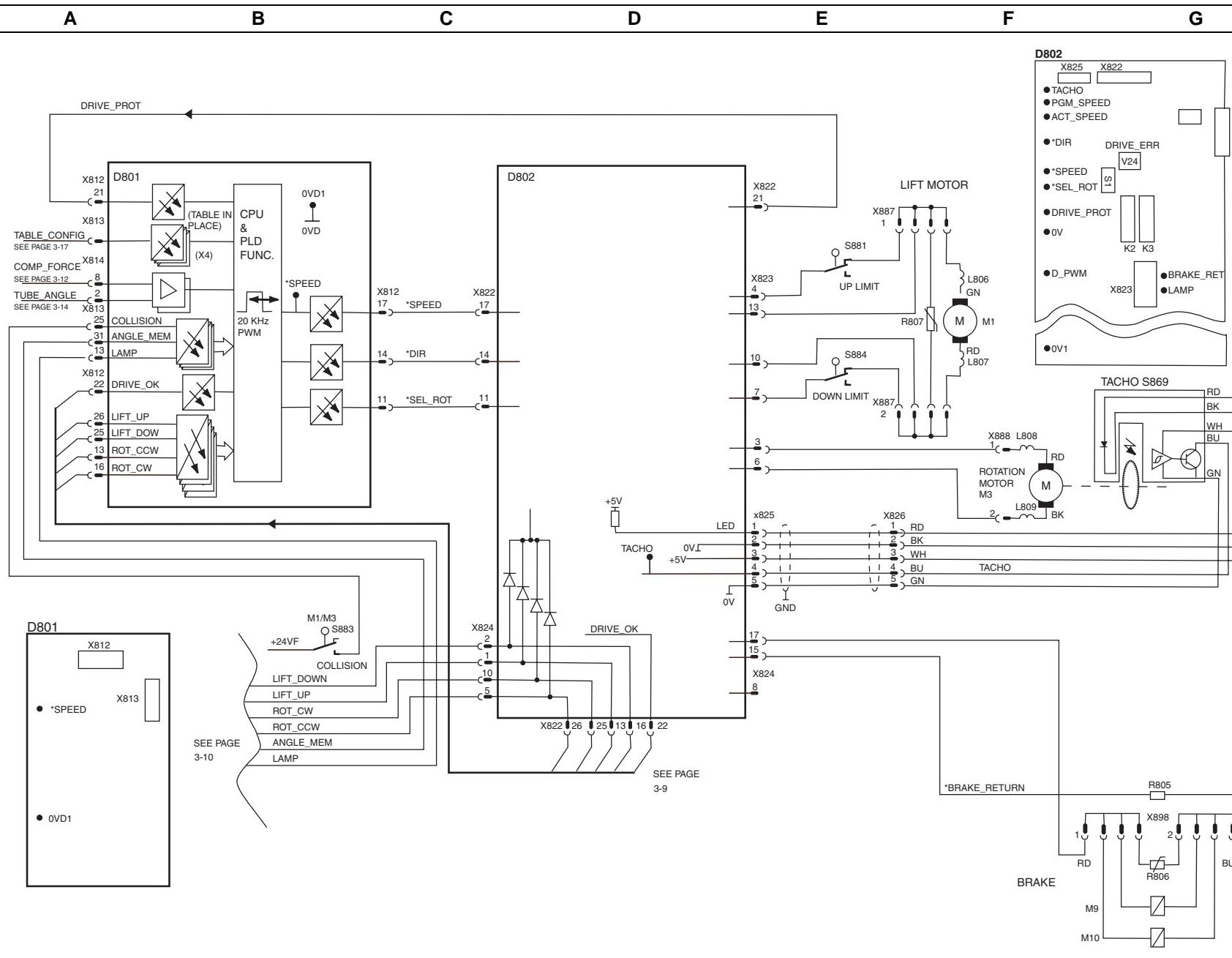
3-7

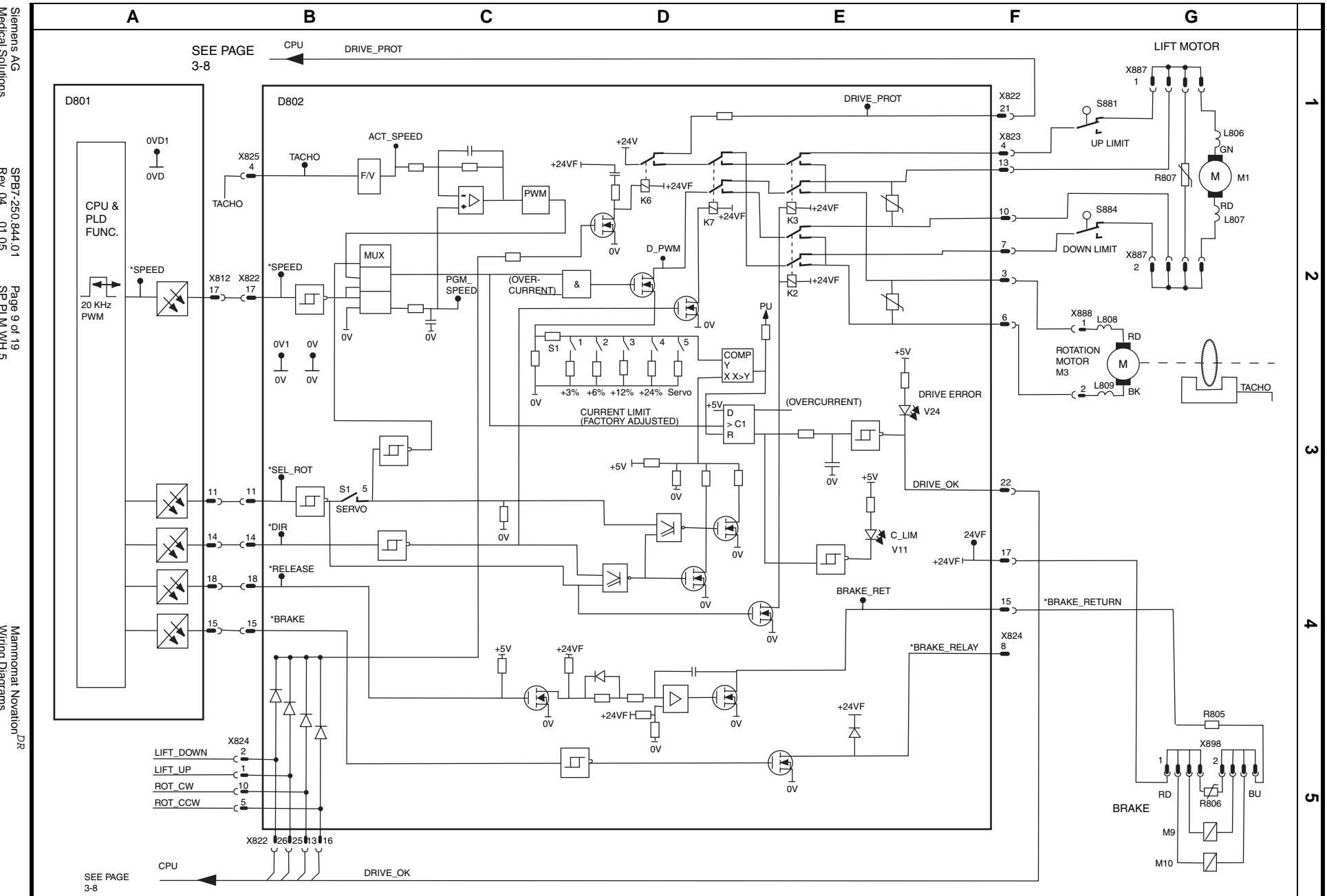


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Rev. 04 01.05 SPP LM WH 5

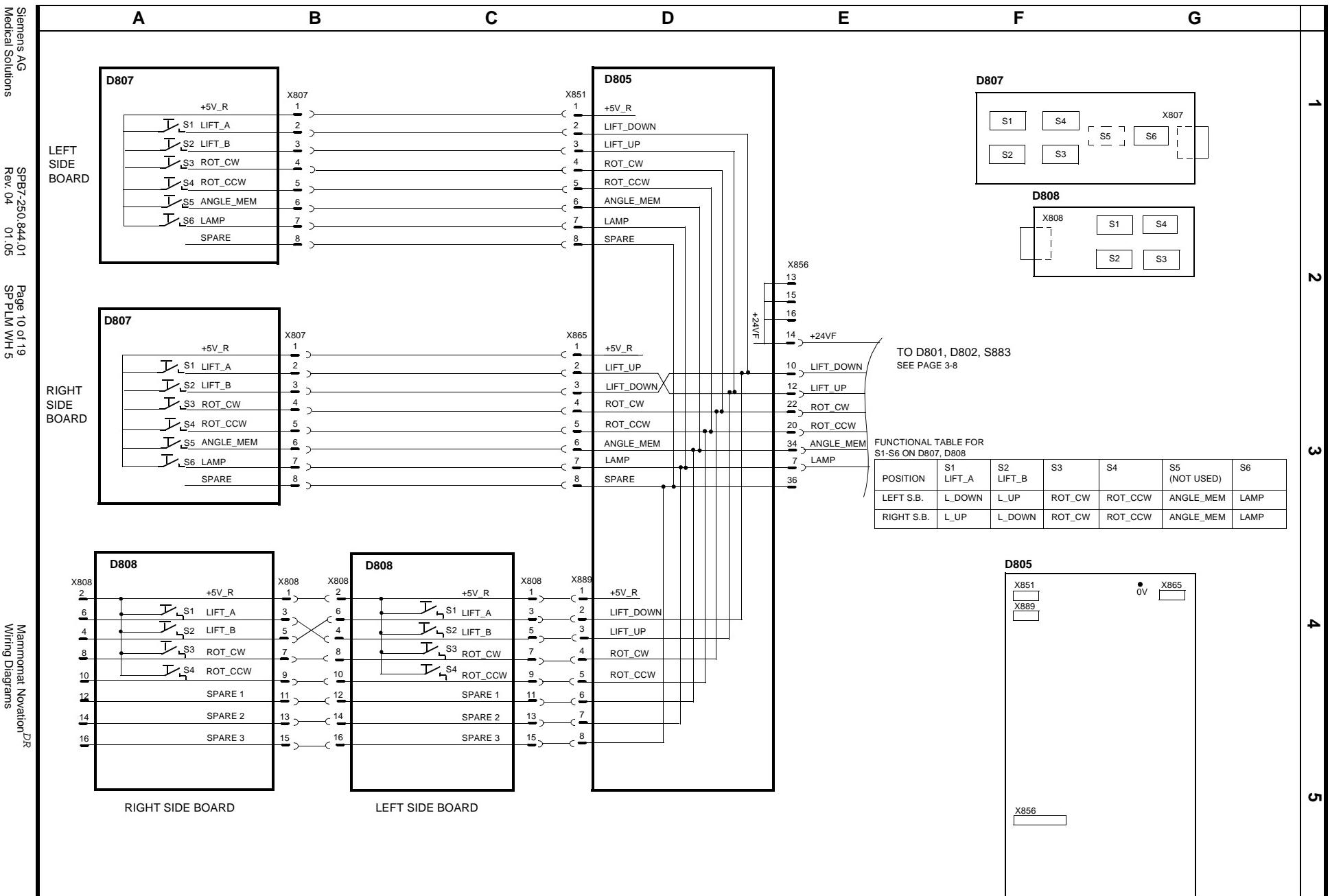
Wiring Diagrams





## LIFT AND ROTATION SWITCHES

X041E



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3-11

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1                    2                    3                    4                    5

A                    B                    C                    D                    E                    F                    G

Siemens AG  
Medical Solutions

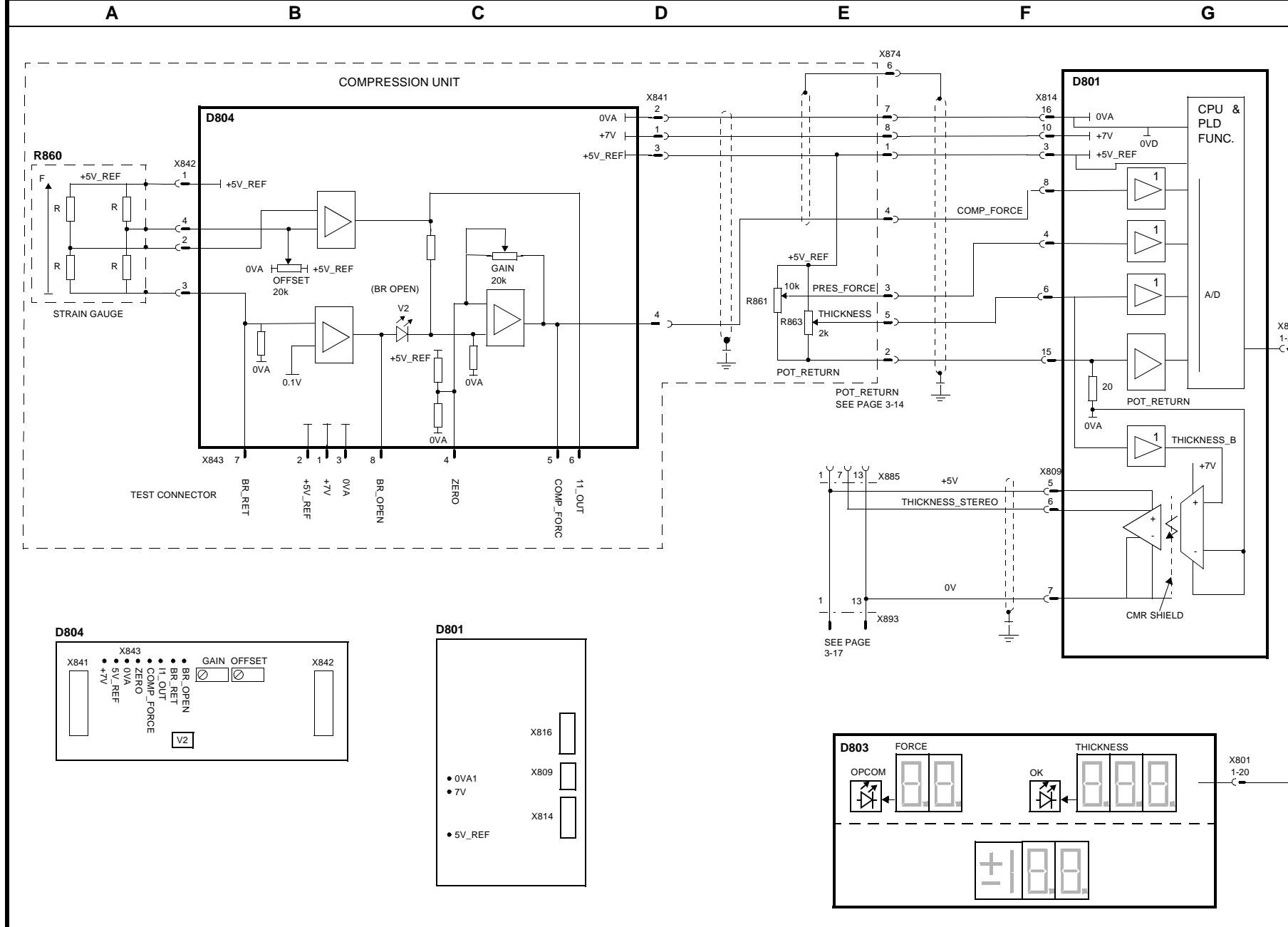
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Rev. 04  
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Page 11 of 19  
S P PLM WH5

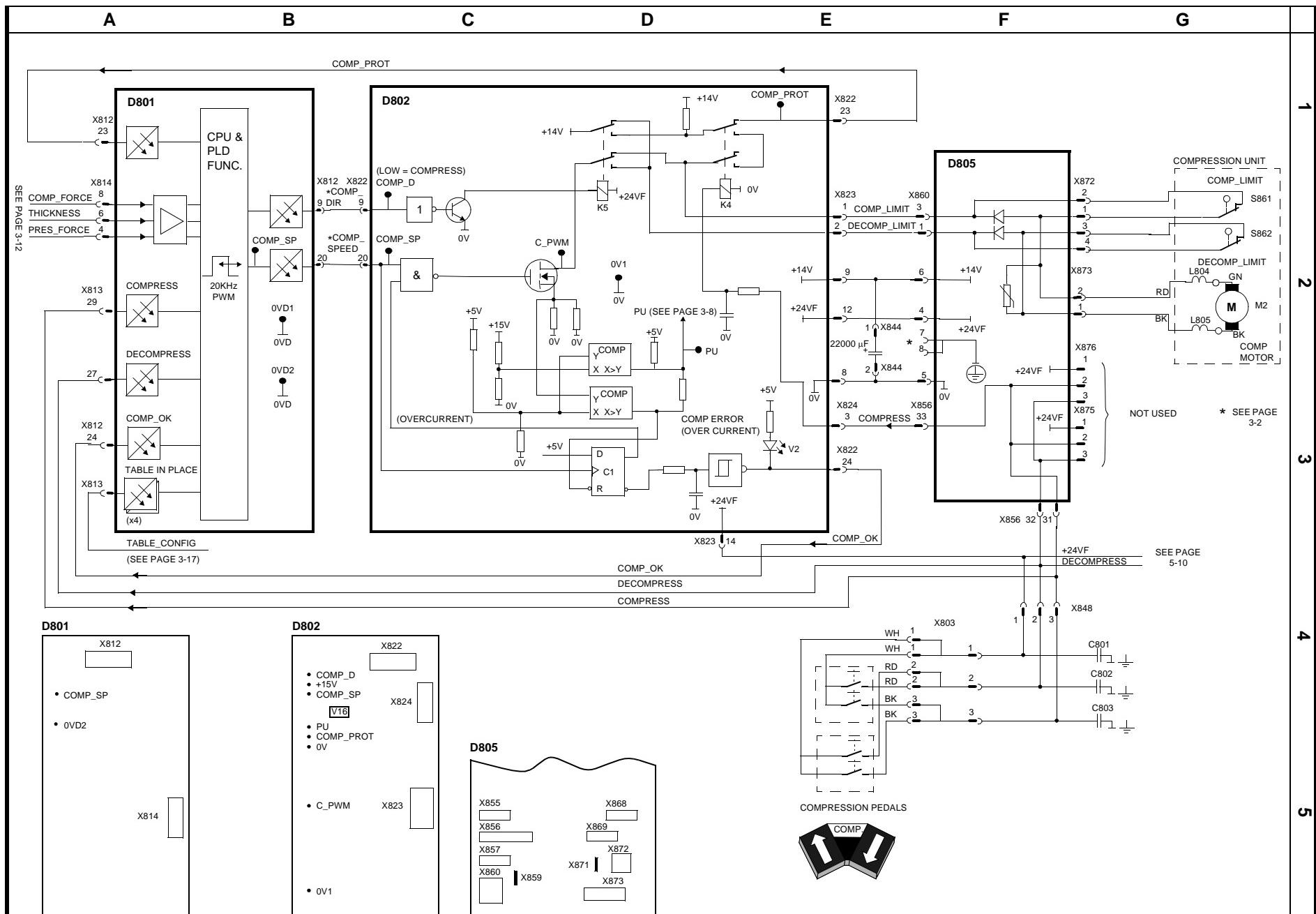
Mammomat Novation<sup>DR</sup>  
Wiring Diagrams

## COMPRESSION MEASUREMENT SIGNALS

X041E



1  
2  
3



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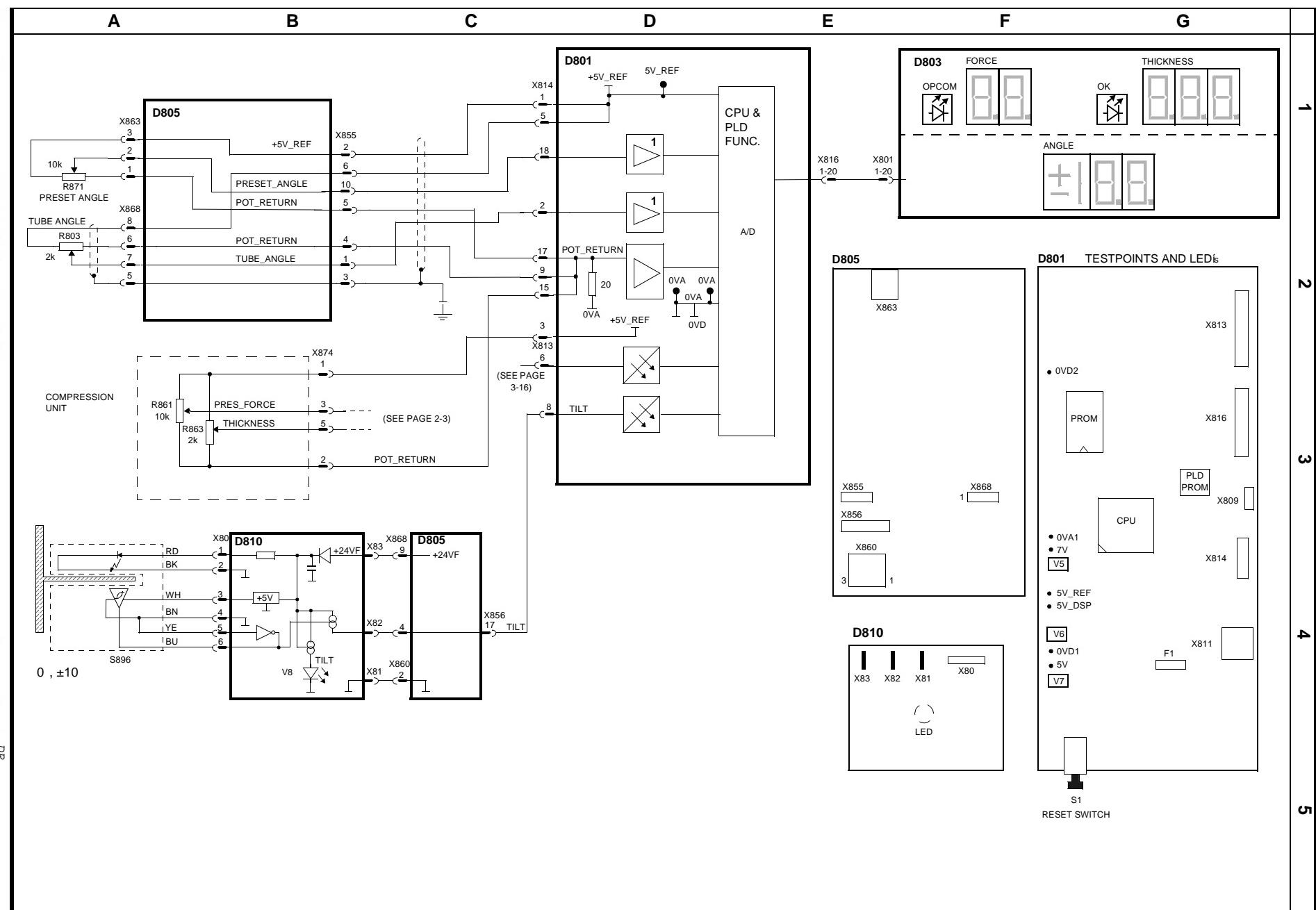
Rev. 04 01.05

SP<sup>®</sup> PLM WH 5

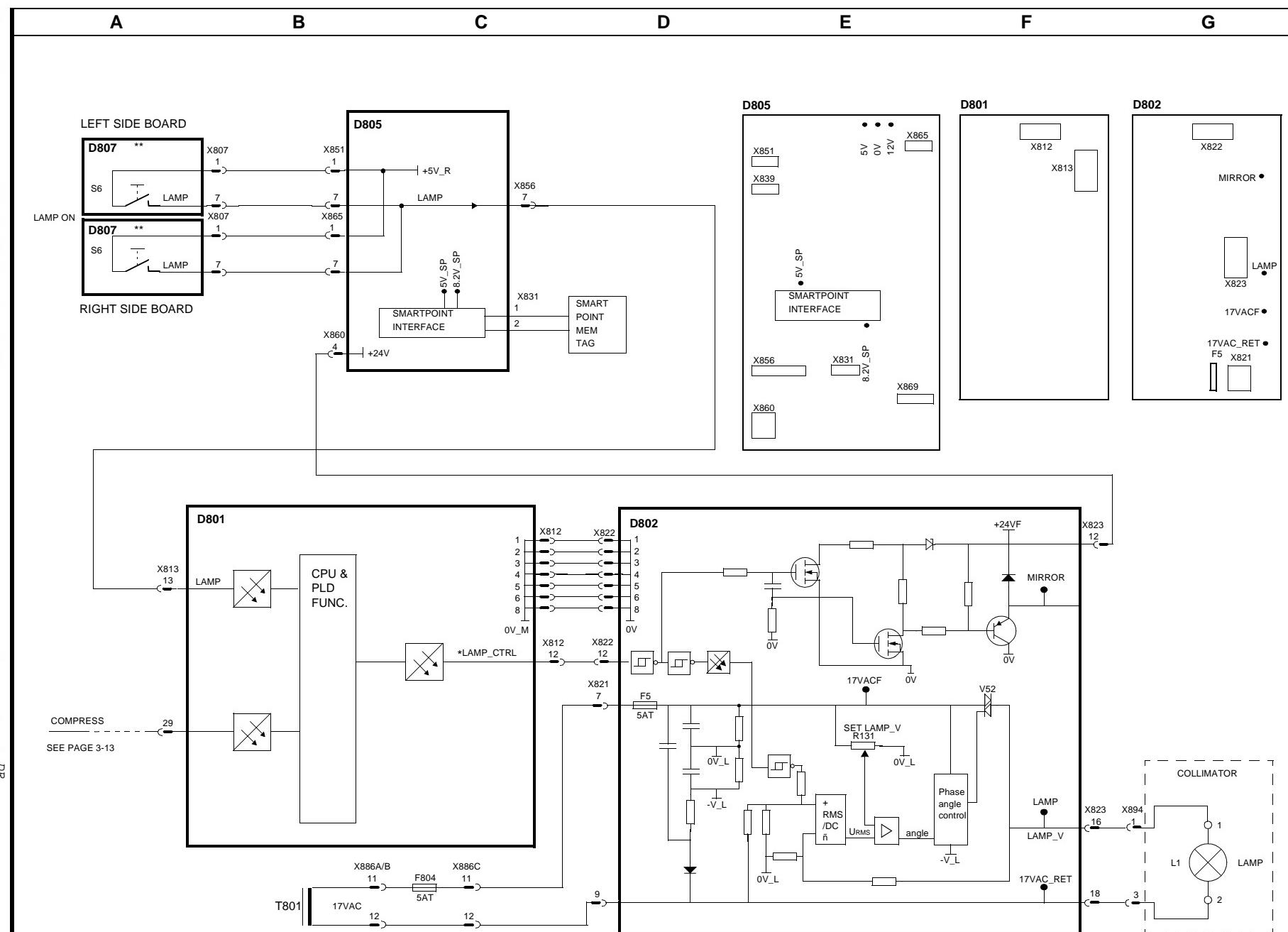
Wiring Diagrams

## TUBE ANGLE MEASUREMENT, POT. RETURN, TILT SIGNALS

X041E

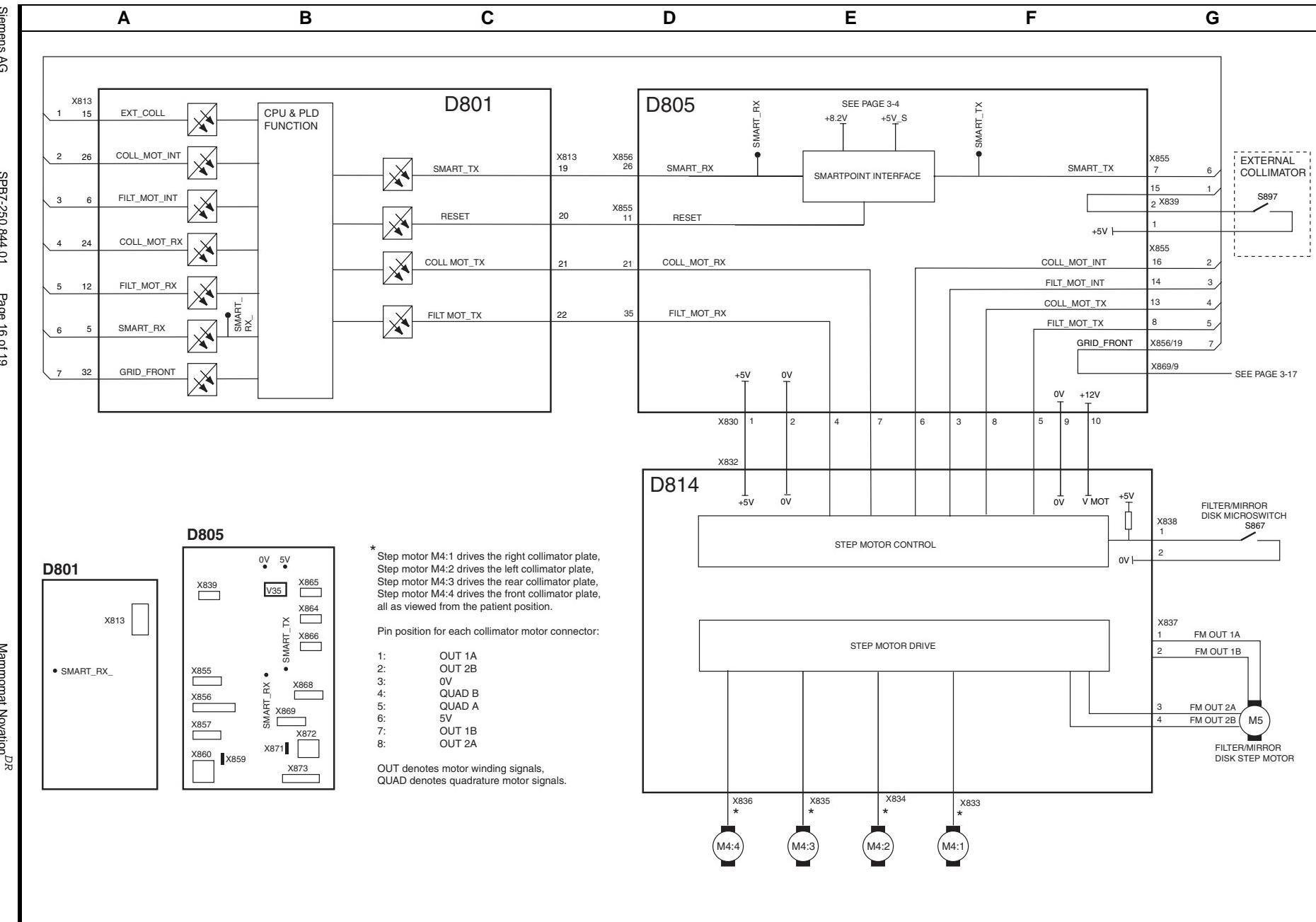


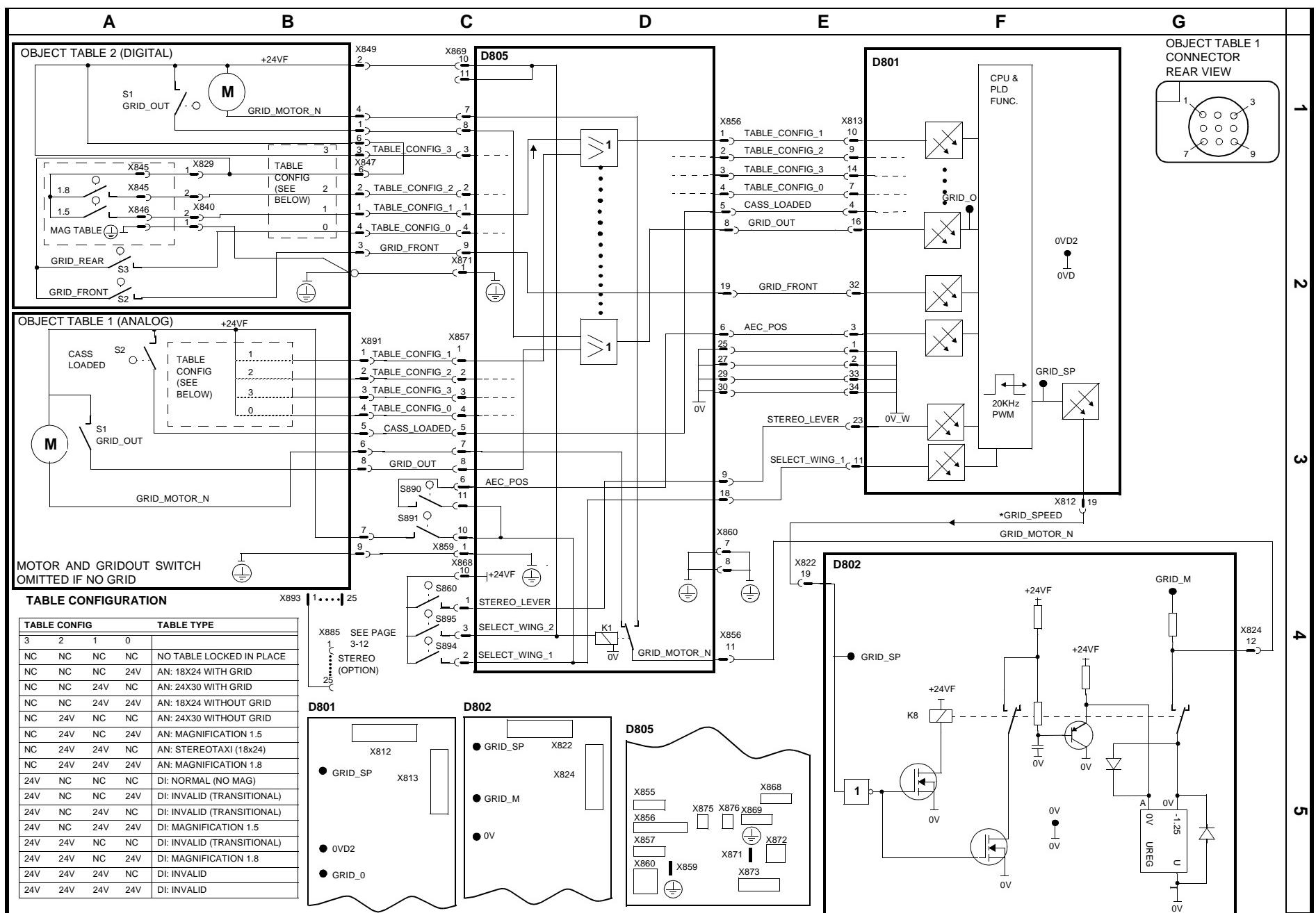
## COLLIMATOR 1

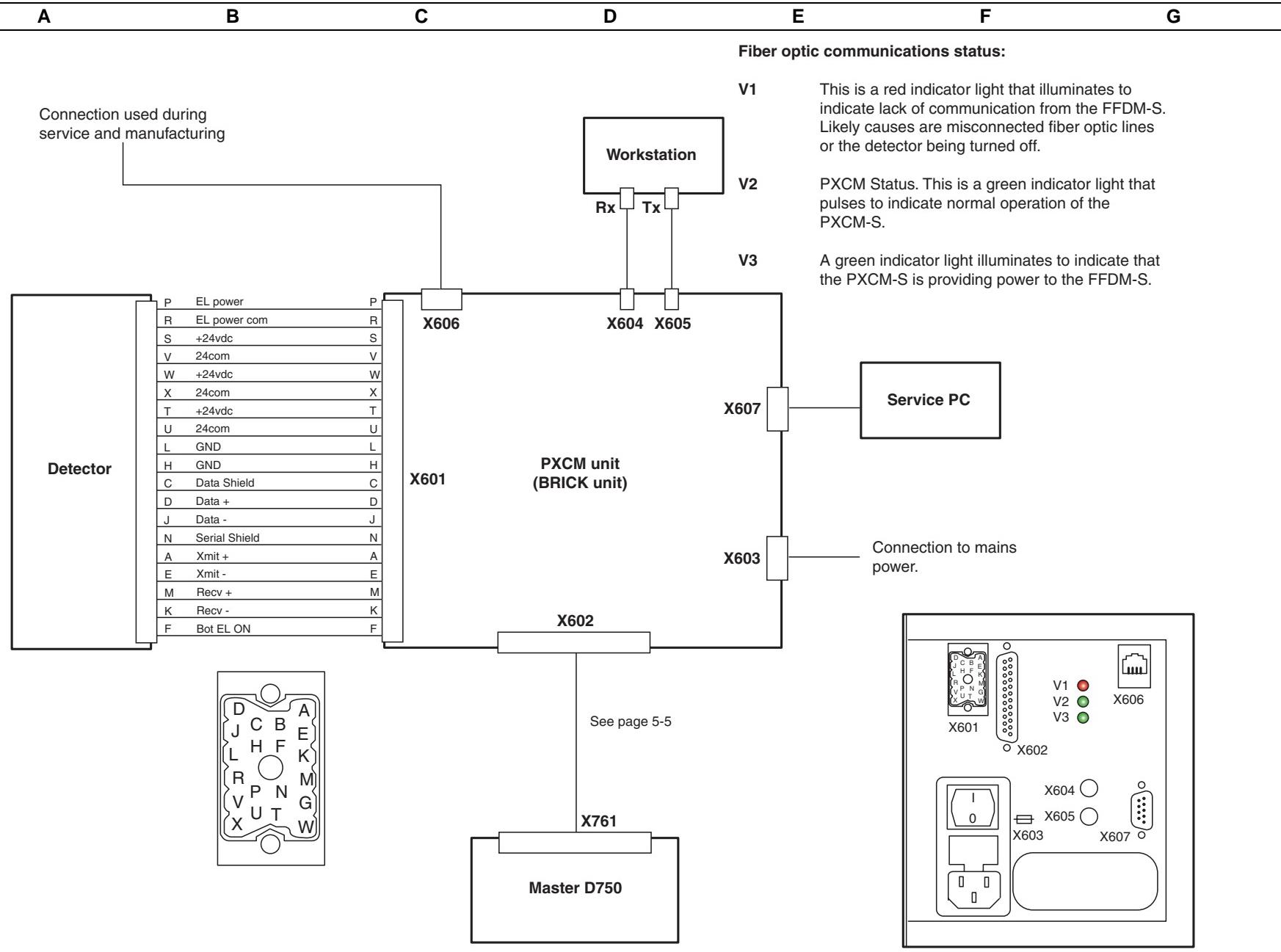
1  
2  
3  
4  
5

## COLLIMATOR 2

1      2      3      4      5







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Page 10 of 13  
SPP LM WH 5

Wiring Diagrams

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1	2	3	4	5
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A      B      C      D      E      F      G

## MAINS VOLTAGE CONNECTION

The mains input can be either 1-phase or 2-phase, 50 or 60 Hz.

### Electrical power to mains input:

Mains voltage      1-phase:      208, 230, 240 and 277 V  $\pm 10\%$   
 or  
 2-phase:      208, 230, 240, 277 and 400 V  $\pm 10\%$

Mains Frequency: 50 or 60 Hz

Maximum load: 10kVA (momentary) and 0.8 kVA (long time load).

Fuse: 25 A (external) 208 -> 400 V.

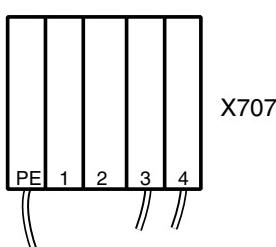
### Power line impedance:

The generator section of the mammomat requires a line impedance not exceeding the maximum values according to the table below:

Nominal input voltage [VAC]	R <sub>i</sub> <sub>max</sub> [Ω]
208	0.45
230	0.50
240	0.60
277	0.65
400	0.85

### Connections:

Power system	Type of connection	Power voltage	Power connections
Singel phase	Phase to neutral	208 V-277 V	Connect to 3 and 4
Two phase	Phase to phase	208 V-400 V phase to phase. Note: Max 277 V phase to neutral/ground allowed.	Connect to 3 and 4. Use two phases (of three) in a normal power distribution system. The left over wires, neutral and the third phase may be connected to terminal 1 and 2. See Fig. 1.



NOV00123

Note 1. PE = Protective Earth

Note 2. Terminals 1 and 2 are not connected internally. Can be used to secure wires when four or five wire power system is used.

Fig. 1

**Modules:**

PB0853	Mains input (Filter unit)
PB0850	Mains input converter
PB0855	AC inverter
PB0854	Tube power supply
PB0851	HV inverter
PB0852	HV Tank

**Fuses:**

- F2 8A/660VAC

Placed inside PB0850 - Mains input converter

Type: Ferraz Shawmut - 660GRB 10-08 / A070GRB08T13 or equivalent.

- F1 5A/660VAC

Placed inside PB0850 - Mains input converter

Type: Ferraz Shawmut - This fuse is used to protect the auxiliary board at unwanted failure, it does not protect internal components and is not intended to be a spare part.

**PC-boards:**

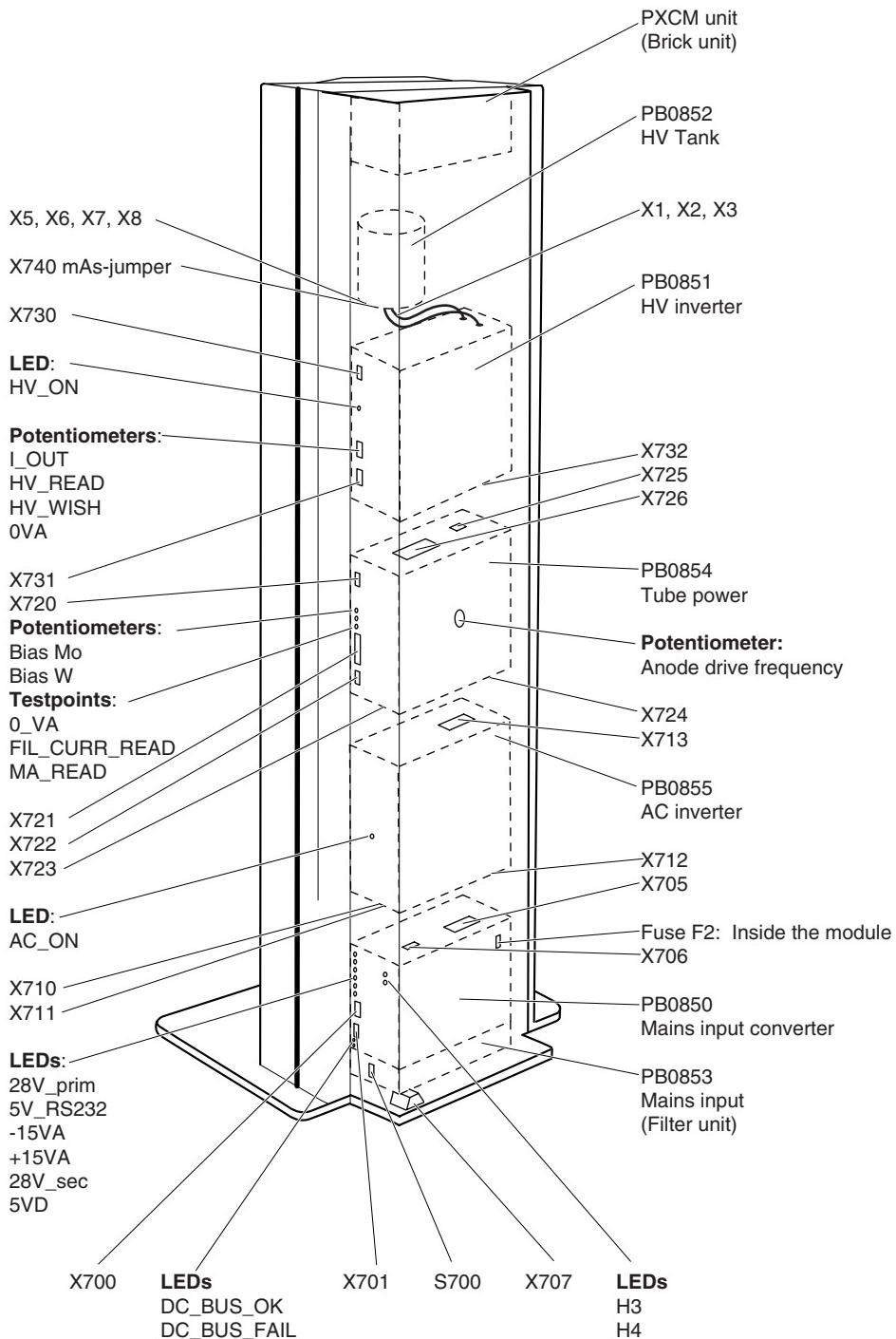
Master board D750

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**Generator description of MAMMOMAT Novation<sup>DR</sup>**

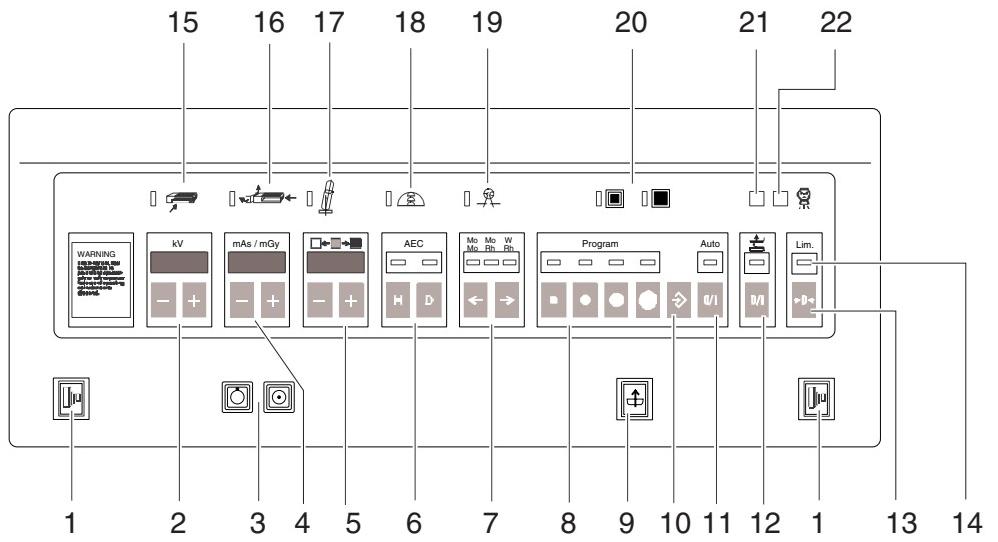


NOV00122

Fig. 2 Back of the stand (seen from the left)

## CONTROL PANEL FUNCTIONS

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NOV/0124

Fig. 3

- 1 Exposure release buttons with green lights. Both buttons must be pressed during the entire exposure. This is to ensure that the operator is standing behind the radiation shield during the exposure.
- 2 +/- KV selection and display
- 3 MAMMOMAT Novation<sup>DR</sup> ON/OFF
- 4 +/- mAs selection and display. In AEC mode (Automatic Exposure Control), the display remains dark before exposure. After the exposure, the mAs value reached during radiography is indicated.  
If the dose calculation option is enabled, the dose value is shown on the same display as the mAs value.
- 5 idr (digital radiography) is displayed on the film density display to indicate that the MAMMOMAT Novation<sup>DR</sup> is ready to be used. If the display is dark the communication with the DR-system is not working. The buttons are not used.
- 6 AEC. These buttons are used to activate AEC mode (Automatic Exposure Control). H stands for low dose exposure and D for high dose exposure.
- 7 Buttons for selection of anode/filter combination in manual mode.
- 8 Buttons for selection of one of four pre-programmed exposure parameter settings.
- 9 Decompression button.
- 10 Button for storing exposure parameter (see pos 8).
- 11 Button to select/deselect auto mode.
- 12 Button to select/deselect automatic decompression after exposure. When off, use foot switch or the knobs for manual decompression or use the decompression button (see pos 9).
- 13 Limit button (acknowledgement). Serves to reset the system after errors, indicated by an error code, or faulty exposures (limit errors), indicated also by the limit lamp and acoustic signal (e.g. limit mAs, dose monitoring, interrupted exposure).
- 14 Limit lamp. Flashing: Tube temperature is above normal. Lit: Limit error (see pos 13).
- 15 Not used for digital mammography.
- 16 Indicates an unknown table configuration. e.g. magnification table not fully inserted.
- 17 Risk of collision between tube head and floor (limit switch is activated).
- 18 Not used for digital mammography.
- 19 Collimator not in correct position or wrong combination of object table and compression plate.
- 20 Focal spot indication. Indicates focus in operation. Small focus is automatically selected, when a magnification table is used.
- 21 Green light indicates that the unit is ready for exposure. This indicator has the same function as the green lights on the stand display and the exposure release buttons.
- 22 Yellow light and an acoustic signal indicate radiation ON.

### **Switches**

<b>Switch</b>	<b>Page</b>	<b>Description</b>
S2	6-1	HV disable; HV = High Voltage Upper position = Normal mode Lower position = HV disable mode
S3	6-1	Manual activation of Power aid unit
S4	6-1	Manual reset of AEC processor

### **Test points**

<b>Test point</b>	<b>Page</b>	<b>Description</b>
5VD_1	6-1	Logic supply voltage: 5 volt digital
0VD_1,2,3,4,5	6-1	Logic supply voltage: 0 volt digital
P15VA	6-1	Logic supply voltage: Positive 15 volt analog
0VA_1,2,3	6-1	Logic supply voltage: 0 volt analog
N15VA	6-1	Logic supply voltage: Negative 15 volt analog
5V_RS232	6-1	Logic supply voltage: 5 volt; for communication with PXCM unit (Brick unit)
0V_RS232	6-1	Logic supply voltage: 0 volt; for communication with PXCM unit (Brick unit)
5VI_RS232	6-1	Logic supply voltage: 5 volt; for communication with Service-PC, Opdima WS and Printer
0VI_RS232	6-1	Logic supply voltage: 0 volt; for communication with Service-PC, Opdima WS and Printer
M_WD_RESET_	6-1	Signal that resets the master CPU and thus causes the entire Mammomat system to restart.
GEN_POWER_ON	6-1	Signal to the generator that turns on the generator and thus the Mammomat system.
DC_BUS_OK	6-1	Signal from the generator, indicating the DC-bus voltage is within its allowed voltage window.
HV_OFF_INT_	6-1	Indicates that the signal M_PLD_HV_OFF_ from the PLD circuit has detected an event that shall terminate or prevent high voltage generation. It causes the signal HV_ON from the Master board to go inactive, which immediately prohibits high voltage generation.
REQ_HV_ON	6-1	Signal from PLD and CPU for generating high voltage and thus start the exposure. It will together with the signal GRID_O_HV_ON set the signal HV_ON.
HV_ON	6-1	Signal set by the signals REQ_HV_ON and GRID_O_HV_ON outputted to the generator. One of two necessary signals, together with the signal EN_HV_ON, to generate high voltage and thus start the exposure. This signal goes low at grid returns, due to GRID_O_HV_ON, thus causing the intermittent loading mode during exposure.
EN_HV_ON	6-1	Signal from the exposure release buttons at the Control panel to the generator. One of two necessary signals, together with the signal HV_ON, to generate high voltage and thus start the exposure.

Test point	Page	Description
GEN_POWERED_ON	6-1	Signal to the PXCM unit (Brick unit), that the power to the Mammomat system has been switched on by the operator.
PREP_DR_DET_	6-1	Signal to the PXCM unit (Brick unit). The <u>positive</u> edge indicates to the Brick that the generator preparation phase for making an exposure has started and requests that the DR detector shall prepare for image acquisition. The <u>negative</u> edge of the signal comes 5 ms after the negative edge of the signal GEN_RDY_FOR_DR_EXP at normal exposure termination, in case the hardware detects an error the negative edge of the signals will coincide. If a tube arc occur the signal will not go inactive.
GEN_RDY_FOR_DR_EXP	6-1	Signal to the PXCM unit (Brick unit). The generator preparation phase has finished and the generator is ready for generating high voltage to the tube (i.e. x-ray). The inactivation of the signal will coincide with negative edge of the signal X_RAY_ON at normal termination of the exposure. In case of an abnormal termination of the exposure, the inactivation of the signal coincides with the inactivation of the signal PREP_DR_DET. If a tube arc occur the signal will not go inactive.
X_RAY_ON	6-1	Signal to the PXCM unit (Brick unit). The exposure is in progress. Note: The signal stays active - at the grid turning points when x-ray actually is off. - at the first two tube arcs when x-ray actually is off.
DR_DET_RDY_FOR_EXP	6-1	The DR detector is making image data acquisition.
DR_SYST_RDY	6-1	The DROC of the DR system indicates that it is ready for an exposure.
DR_DET_ERR_	6-1	The DR system indicates to the generator that it has detected an error.
HV_SET	6-1	Analog output signal to the generator for setting the magnitude of the tube voltage (high voltage). The relation between the tube voltage and the analog control signal is 5kV/V.
HV_ACT	6-1	Analog input signal HV_ACT, from the generator, that is proportional to the true tube voltage. The relation between the tube voltage and the analog signal is 5kV/V.
MA_SET	6-1	Analog output signal to the generator for setting the magnitude of the tube current. The relation between the tube current and the analog control signal is 40mA/V.
MA_ACT	6-1	Analog input signal MA_ACT, from the generator, that is proportional to the true tube current. The relation between the tube current and the analog signal is 40mA/V.
FIL_CURR_SET	6-1	Analog output signal to the generator for setting the magnitude of the filament current. The relation between the filament current and the analog control signal is 1A/V.
FIL_CURR_ACT	6-1	Analog input signal FIL_CURR_ACT, from the generator, that is proportional to the true filament current. The relation between the filament current and the analog signal is 1A/V.

Test point	Page	Description
ACC_ANODE	6-1	<p>Signal to the generator to start the anode rotation by accelerating the stator of the tube. The acceleration power (AC current) to the tube continues as long as the bit is set.</p> <p>Note, the generator stops the acceleration power to the tube if this signal is set longer than about 2.9 sec.</p>
BRAKE_ANODE	6-1	<p>Signal to the generator to stop the anode rotation by braking the stator of the tube. The braking power (DC current) to the tube continues as long as the bit is set.</p> <p>Note, the generator stops the braking power to the tube if this signal is set longer than about 7.4 sec.</p>
ANODE_FREQ	6-1	<p>Signal from the generator for measurement of the anode rotation speed. The frequency of the signal is equal to the anode rotation frequency.</p> <p>Note, PLD measurement of this signal starts 200 ms after the signal ACC_ANODE goes low, mean value of 10 pulses is calculated.</p>

**Switches:**

Switch	Page	Module	Description
S700	4-5	Mains input (Filter unit)	On/Off circuit breaker for mains input, inside the covers. The breaker is intended for service/maintenance as an extra possibility to turn off the mains for safety at work with the unit. It shall be in On position when the covers are mounted. The breaker also protects the generator, it trips at overcurrent (30A) plus has a trip coil used for DC-bus overvoltage protection.

**Potentiometers**

Potentiometer	Page	Module	Description
Bias Mo	5-6	Tube power supply	Adjustment of bias voltage for Molybden (Mo).
Bias W	5-6	Tube power supply	Adjustment of bias voltage for Tungsten (W).
Anode drive freq.	5-7	Tube power supply	Adjustment of drive freq. 3 - 5 Hz from its nominal value, for decreasing noise that can occur due to mechanically vibrations from the tube assembly.

**Test points**

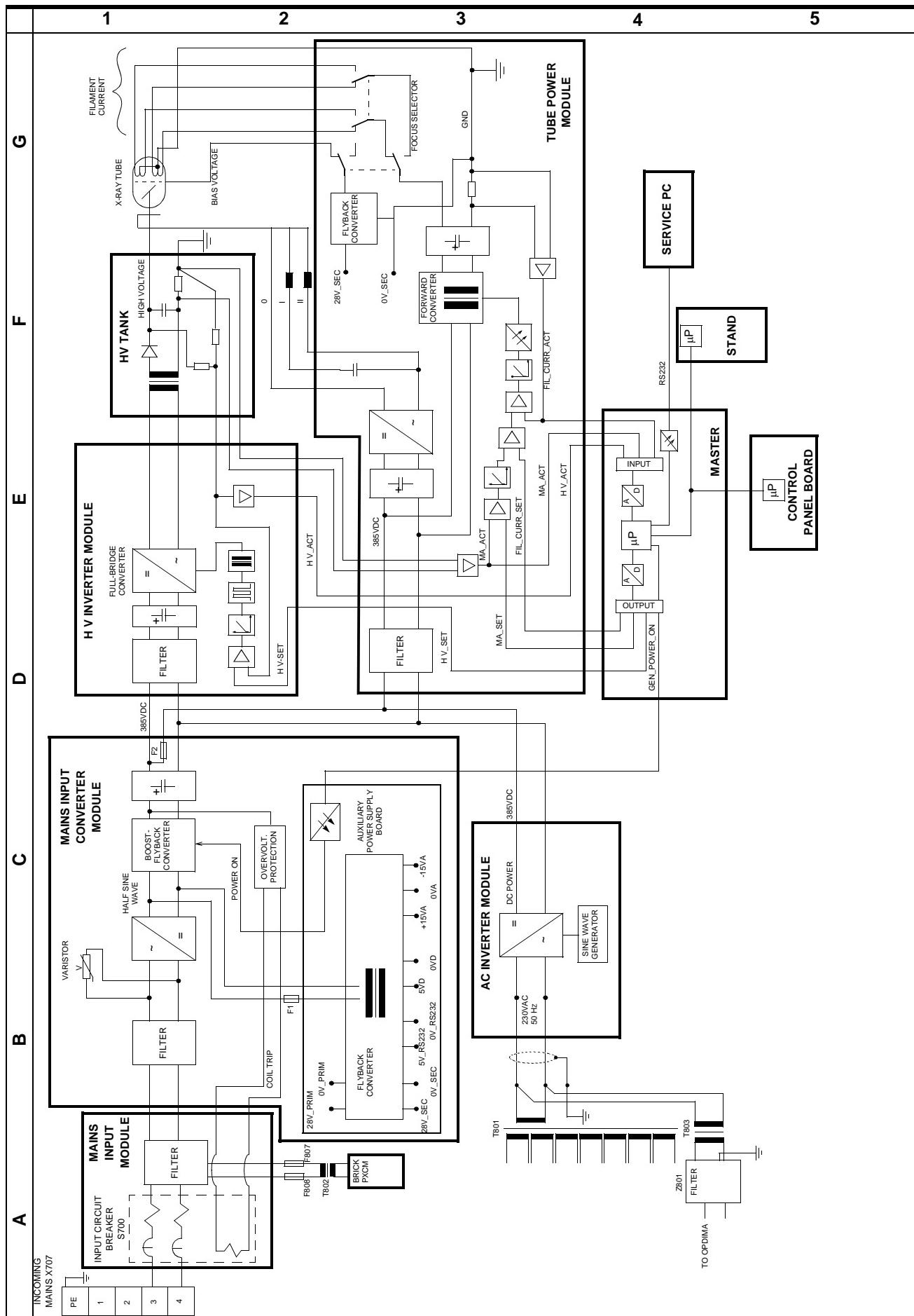
Test point	Page	Module	Description
0VA	5-6	Tube power supply	Logic supply voltage: 0 volt analog  Note: 0VA = 0V_sec
FIL_CURR_READ	5-6	Tube power supply	Analog signal proportional to the true filament current. The relation between the filament current and the analog signal is 1A/V.
MA_READ	5-6	Tube power supply	Analog signal proportional to the true tube current. The relation between the tube current and the analog signal is 40mA/V.
I_OUT	5-8	HV inverter	Analog signal proportional to the output inverter current fed to the HV tank.
HV_READ	5-8	HV inverter	Analog signal proportional to the true tube voltage. The relation between the tube voltage and the analog signal is 5kV/V.
HV_WISH	5-8	HV inverter	Analog control signal for setting the magnitude of the tube voltage (high voltage). The relation between the tube voltage and the analog control signal is 5kV/V.
0VA	5-6	HV inverter	Logic supply voltage: 0 volt analog  Note: 0VA = 0V_sec

**LEDs:**

<b>LED</b>	<b>Page</b>	<b>Module</b>	<b>Description</b>
28V_prim	4-5	Mains input converter	Logic supply voltage: 28-30 volt, only to the generator modules.  Note: The voltage is hazardous.
5V_RS232	4-5	Mains input converter	Logic supply voltage: 5 volt; for communication with PXCM unit (Brick unit)
-15VA	4-5	Mains input converter	Logic supply voltage: Negative 15 volt analog
+15VA	4-5	Mains input converter	Logic supply voltage: Positive 15 volt analog
28V_sec	4-5	Mains input converter	Logic supply voltage: 28-30 volt, only to the generator modules.
+5VD	4-5	Mains input converter	Logic supply voltage: 5 volt digital
DC_BUS_OK	4-5	Mains input converter	The DC-bus voltage is OK, that is, inside its upper and lower limits.  Note: The LED can only be lit when the D750 Master board gives a GEN_POWER_ON signal.
DC_BUS_FAIL	4-5	Mains input converter	The DC-bus voltage is outside its upper or lower limits.  Note: The LED can only be lit when the D750 Master board gives a GEN_POWER_ON signal.
H3	4-5	Mains input converter	The DC-bus voltage is present (>15 volt) to the AC inverter and to the Tube power supply.  Note: If LED H3 not is lit but H4 is lit, indicates the fuse F2 inside the Mains input converter has blown and need to be replaced.
H4	4-5	Mains input converter	The DC-bus voltage is present (>15 volt) to the HV inverter.
AC_ON	4-5	AC inverter	The AC output voltage is present.
HV_ON	4-5	HV inverter	The EN_HV_ON signal is set and thus x-ray exposure is on.

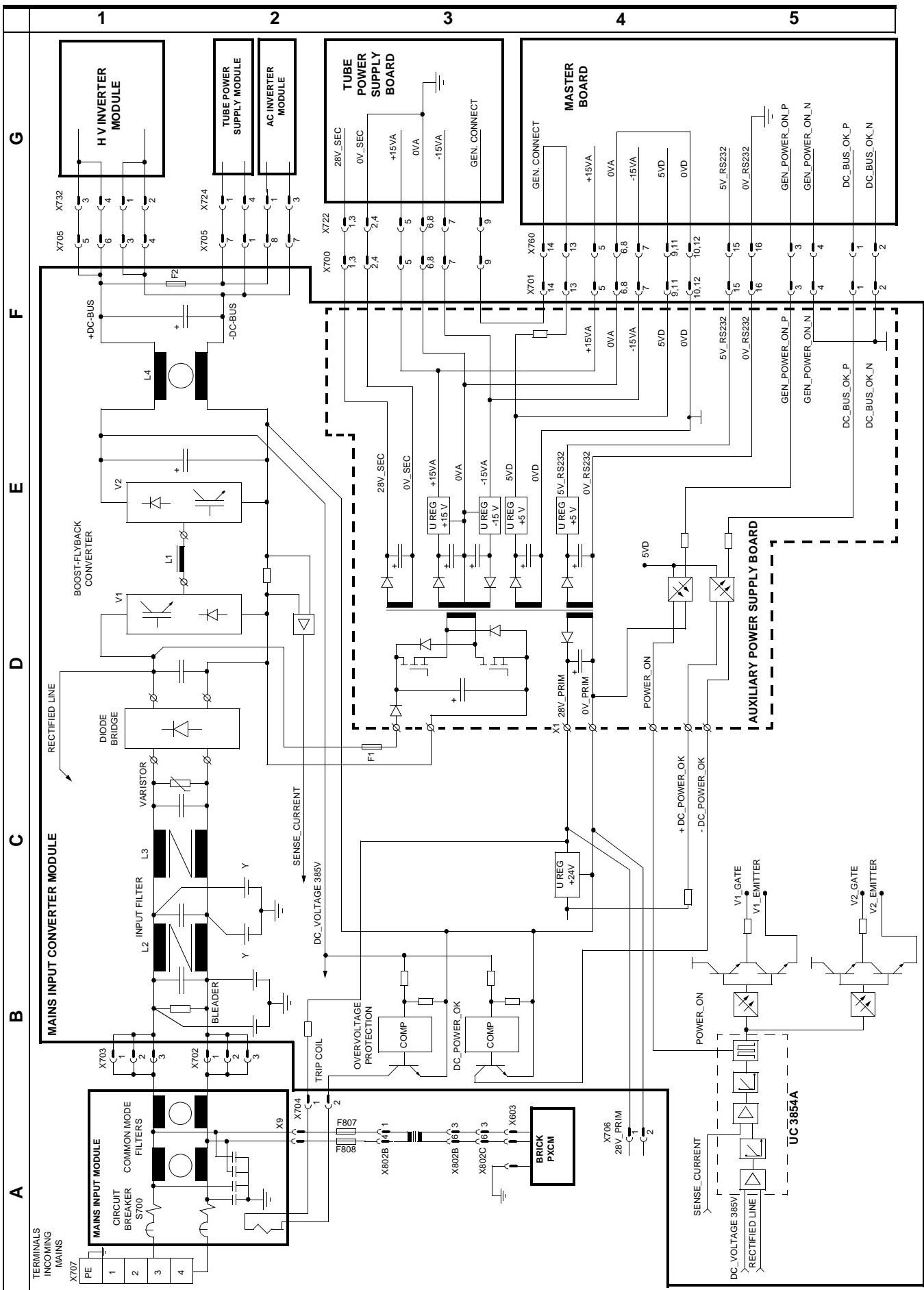
**Comment:** Before making any service/maintenance on the generator modules both LEDs H3 and H4 shall be off, thus making sure the DC-bus voltage not is present.  
The DC-bus voltage discharges below 60 volt within 3 minutes.

## GENERATOR: BLOCK DIAGRAM



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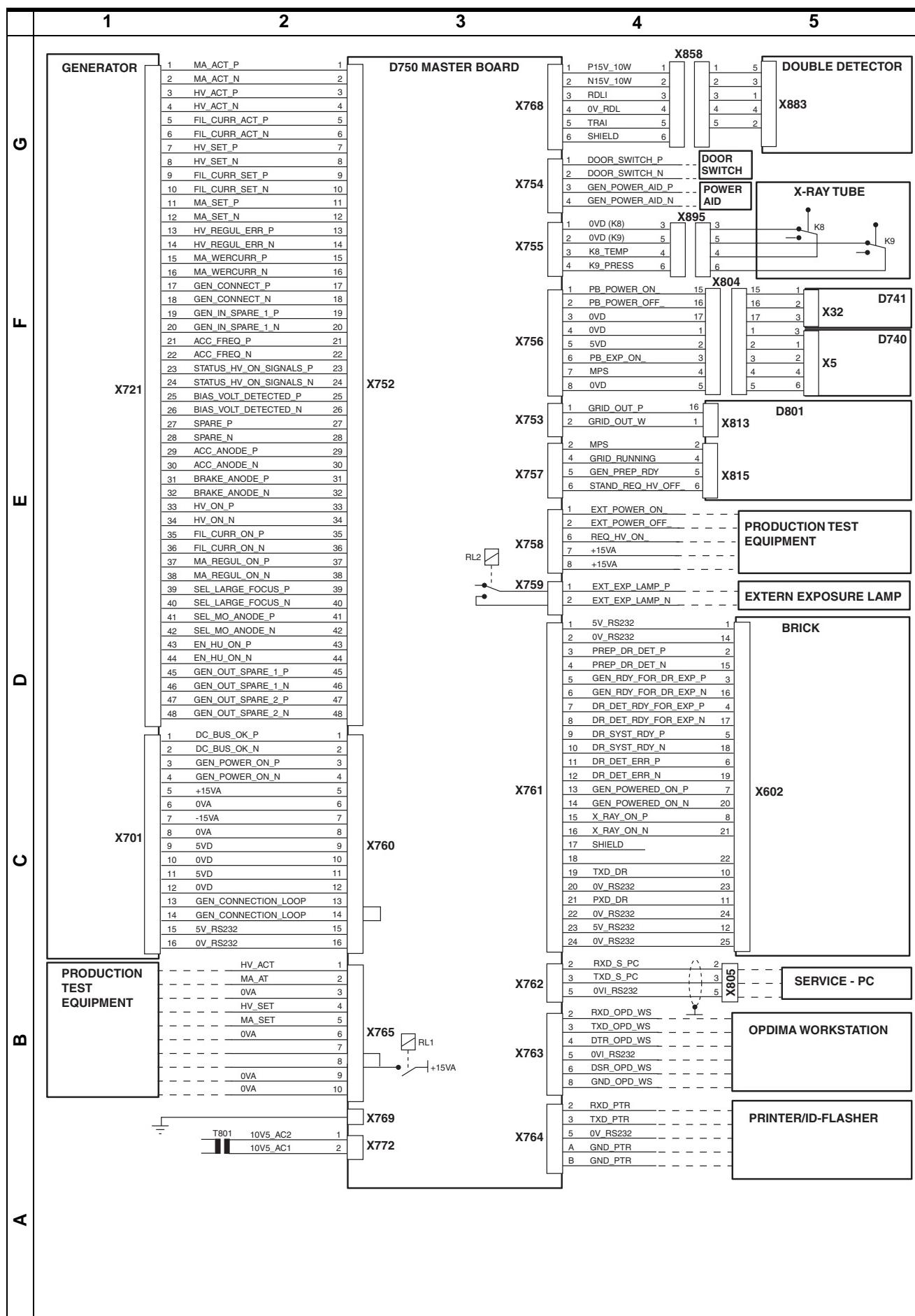


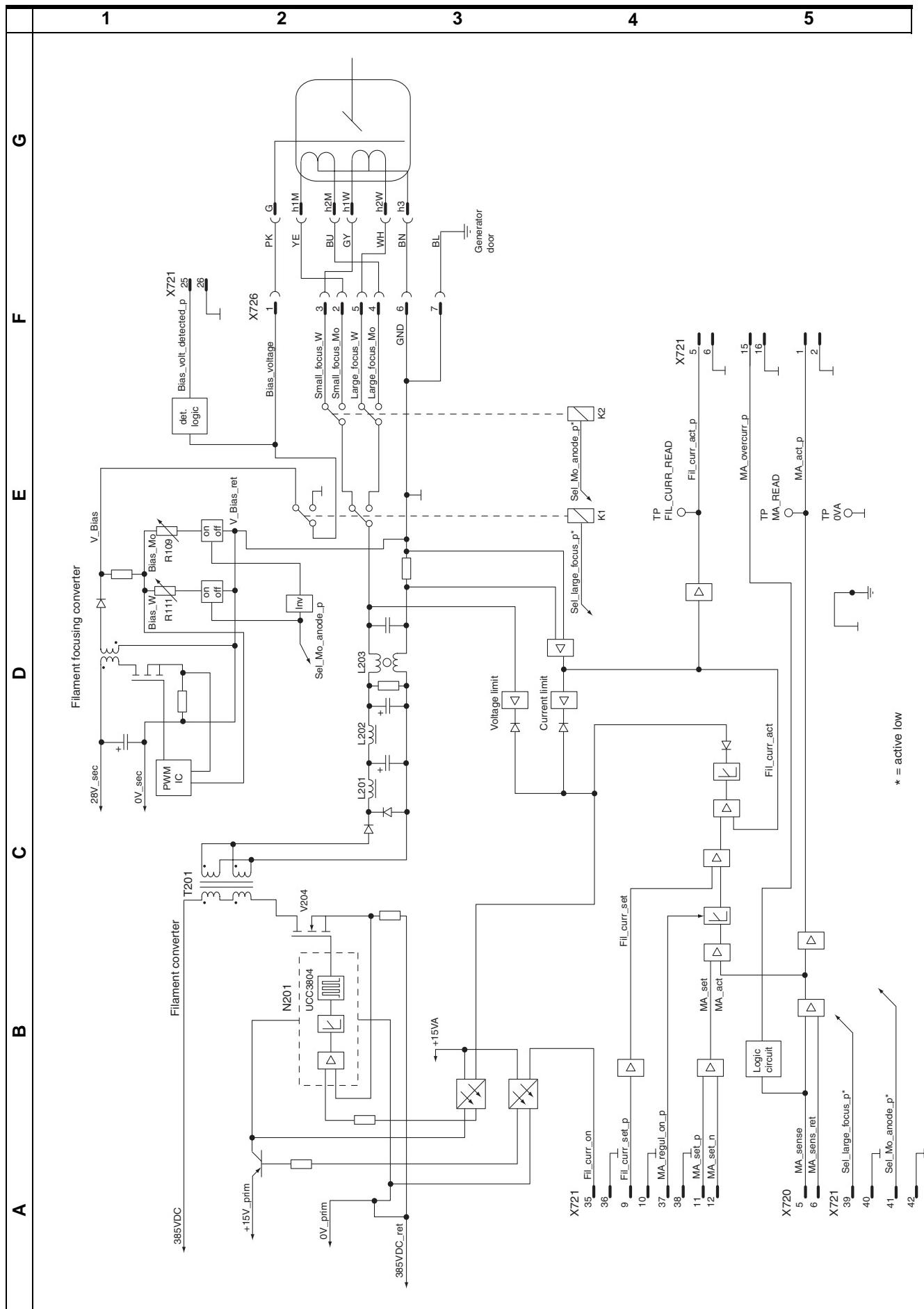
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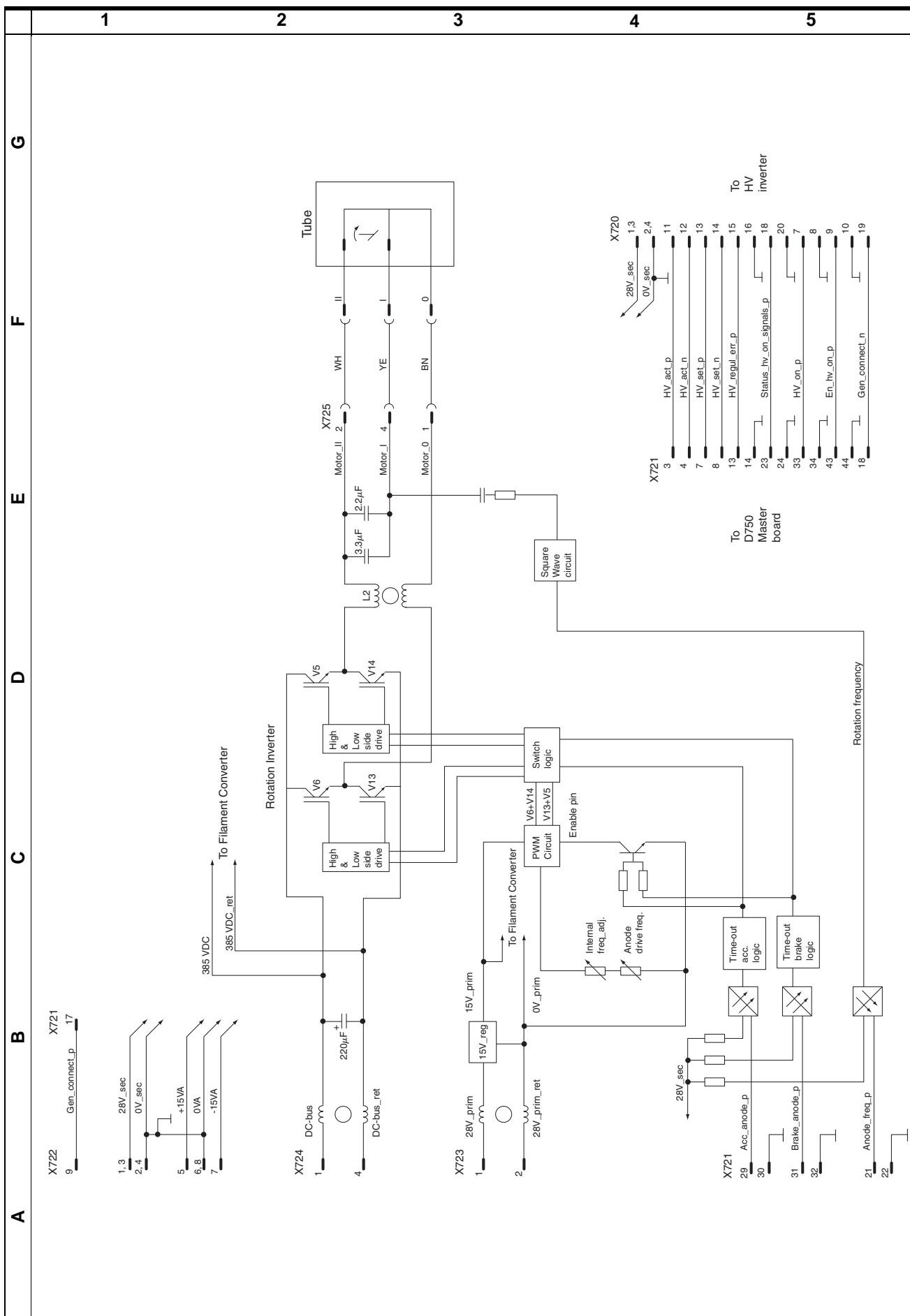
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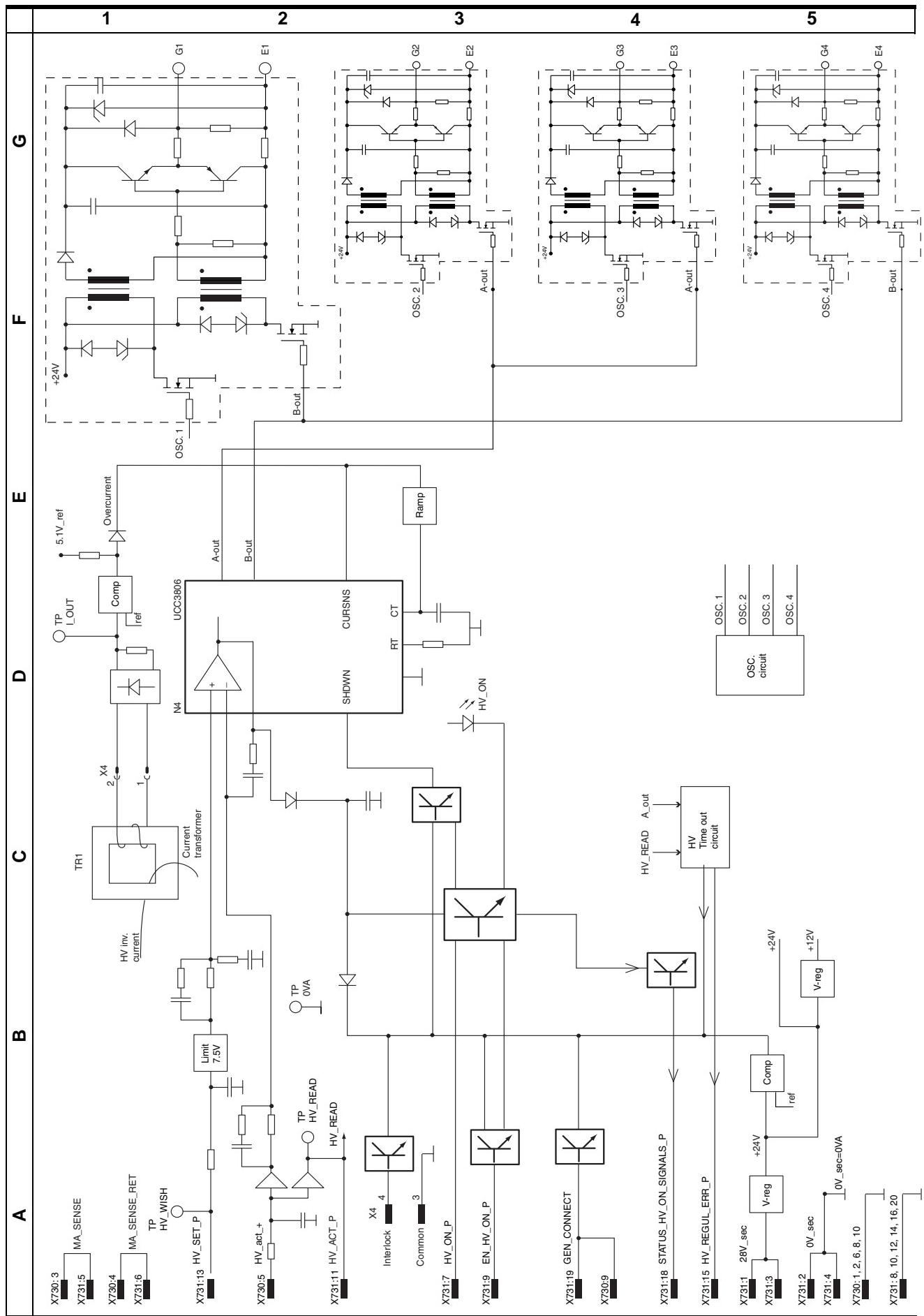
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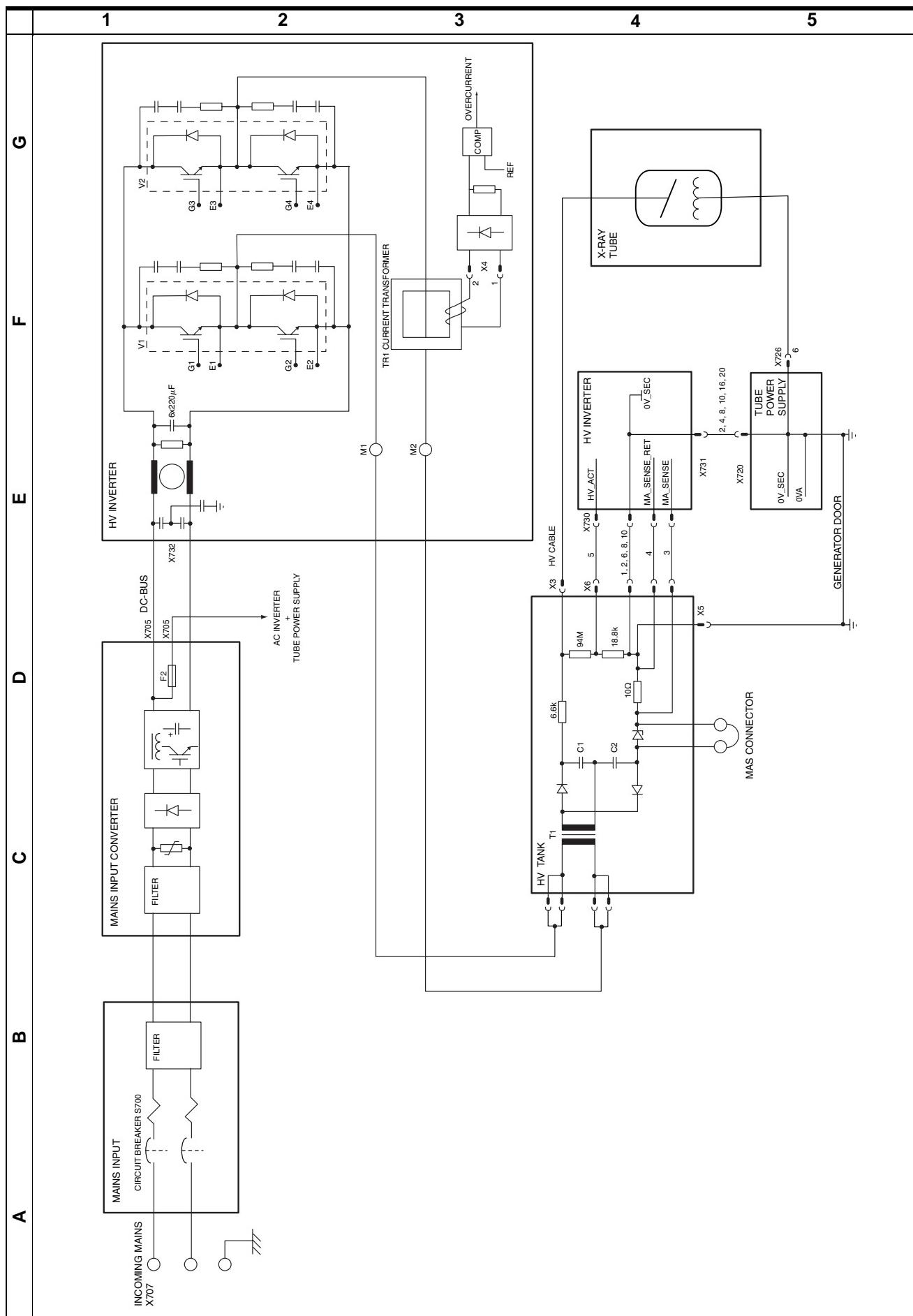
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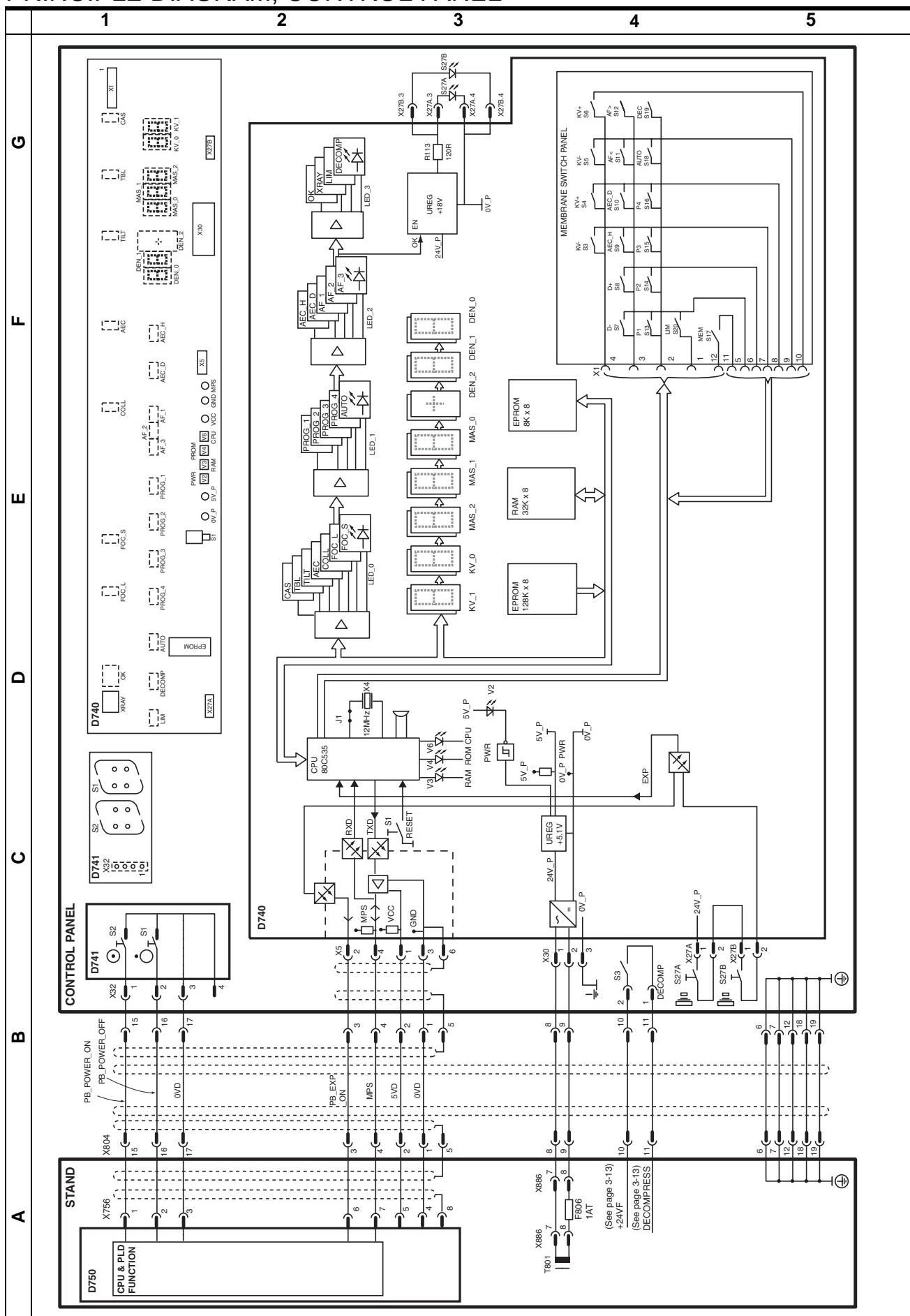


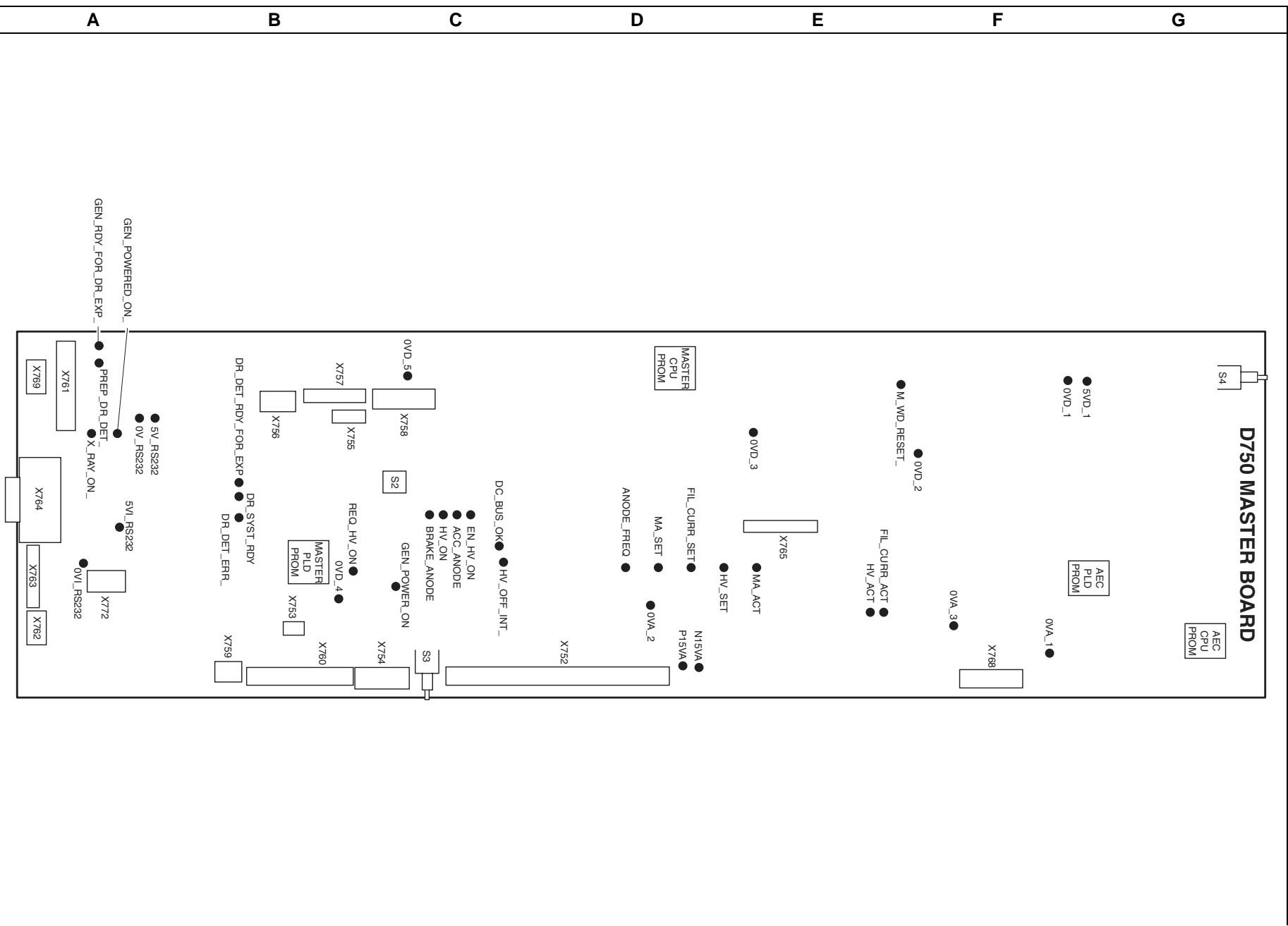


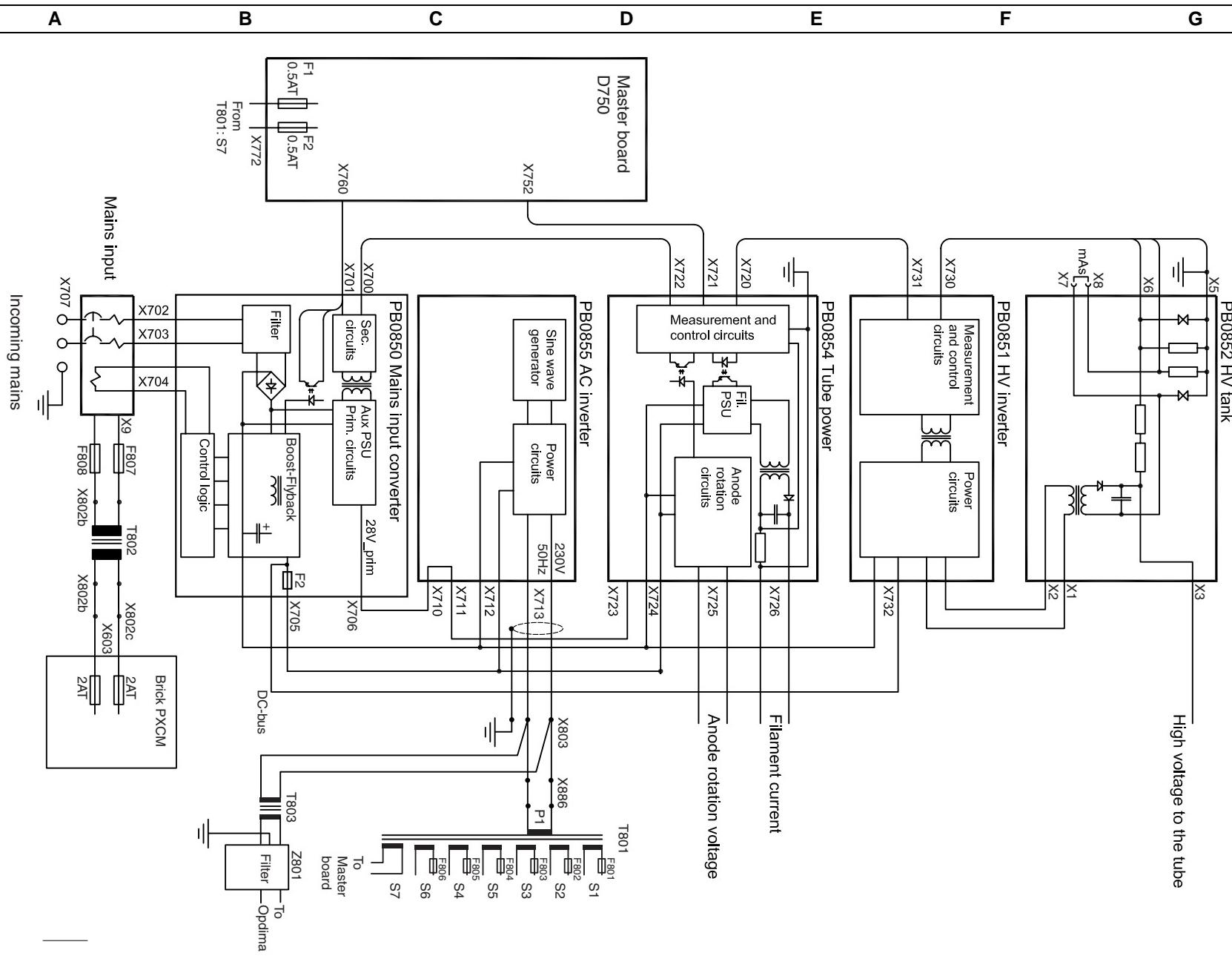
**GENERATOR - HV INVERTER:  
PRINCIPLE DIAGRAM, CONTROL LOGIC**




## PRINCIPLE DIAGRAM, CONTROL PANEL







## Changes to previous version

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Chapter	Page	Change
1	1	New chapter, system overview.
1	2	New chapter, system overview - stand
2	5	Updated with page references.
2	6	Updated with page references.
2	8	Updated with page references.
2	9	Updated.
2	10	Updated with page references.
2	12	Updated with page references.
2	13	Updated with signal name, Thickness_B.
2	14	Updated with page references.
3	2	Updated.
3	3	New chapter, mains connection, power supply CPU.
3	4	New chapter, power supply motor control.
3	5	New chapter, display.
3	6	Updated.
3	7	New chapter, tube, temperature monitoring.
3	8	New chapter, lift and rotation.
3	9	New chapter, lift and rotation motor drive.
3	10	New chapter, lift and rotation switches.
3	11	This page is intentionally left blank.
3	12	New chapter, compression measurement signals.
3	13	New chapter, compression motor drive.
3	14	New chapter, tube angle measurement, pot. return, tilt signals.
3	15	Updated.
3	16	Updated.
3	17	Updated.
3	18	New chapter, PXCM unit (Brick unit)

**Changes to previous version**

Chapter	Page	Change
5	2	This page is intentionally left blank.
5	10	New chapter, principle diagram, control panel.
6	1	Updated.
7	1	Updated with changes to previous version.
7	2	Updated with changes to previous version.